

Application Performance: Altix vs. the Rest

Georg Hager

**Computing Center, University of Erlangen
(RRZE)**

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Agenda



- **RRZE**
- **Altix Basics**
 - **Architecture**
 - **Software**
 - **Competitors**
- **Applications**
 - **CFD**
 - **SIP Solver (OpenMP)**
 - **Physics**
 - **DMRG (SCSL)**
 - **DMRG (OpenMP)**
- **Conclusions**

RRZE Machine Structure



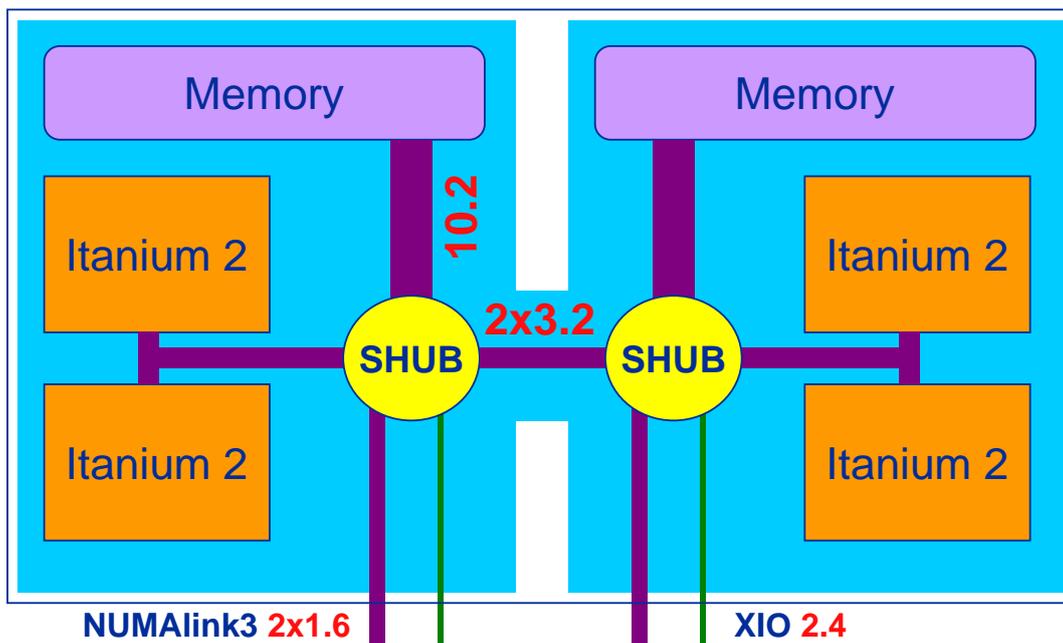
- **Fujitsu VPP300**
 - 8 CPUs @ 2.2 GFlops, 2 GB
 - Installed 1997
- **SGI Origin 3400**
 - 28 CPUs @ 500 MHz (R14k)
 - 56 GB
 - Installed June 2001
- **IA32 Cluster**
 - 86x2 Xeon 2.66 GHz
 - Gigabit Ethernet
 - Installed April 2003
- **SGI Altix 3700**
 - 28 CPUs @ 1.3 GHz
 - 112 GB
 - Installed December 2003
- **Several test systems**
 - Opteron, Xeon, IT1, IT2



Altix Basics

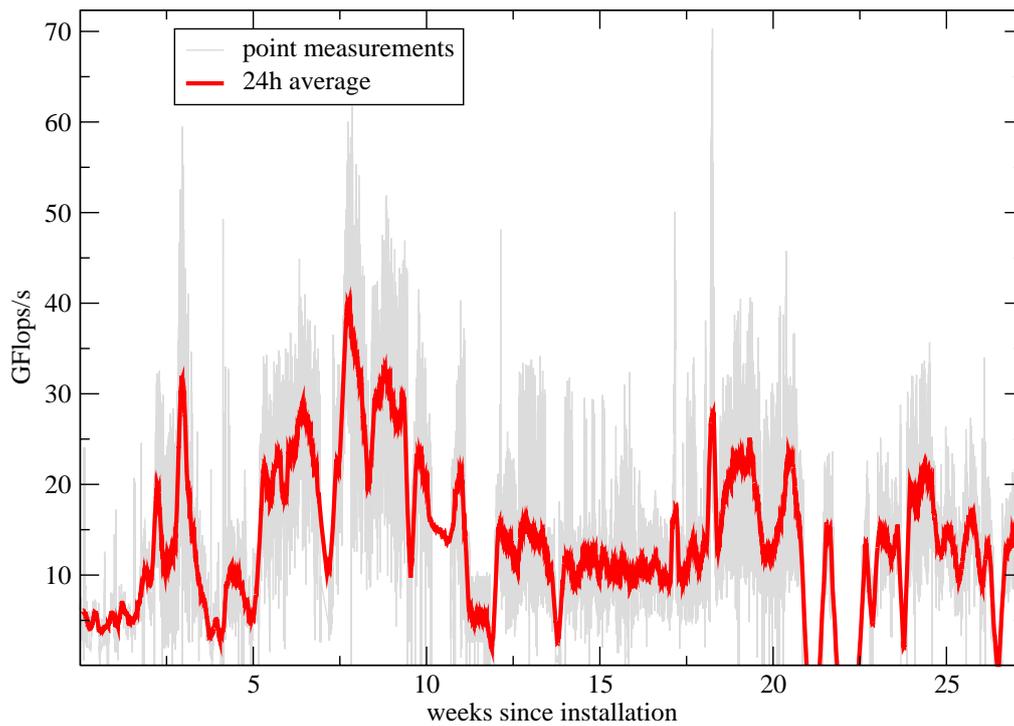
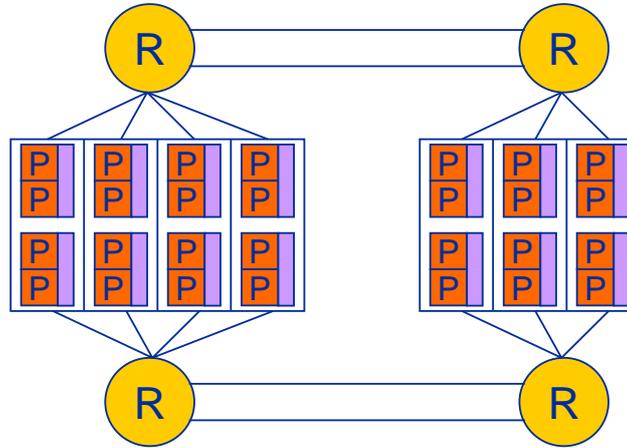


- **Dual-Itanium2 nodes**





- ccNUMA via NumaLink3/4
 - Layout of Altix at RRZE:





- **OS: Linux w/ ProPack 2.4**

- **Profiling tools**
 - pfmon
 - profile.pl
 - histx (cool, but no match for Speedshop)

- **Compilers**
 - Intel 7.1 and 8.0, F90 and C++
 - gcc 3.0.4



- **IBM p690**
 - 32-CPU ccNUMA
 - dual Core Power4
- **NEC TX7**
 - 32-CPU ccNUMA, Itanium 2
 - 4 CPUs per memory path
- **NEC SX6**
 - Vector CPU, 0.5 words/flop
 - Shared memory node with 8 CPUs, full bandwidth
- **Intel Xeon systems**
 - IA32 architecture, high clock rates
- **AMD Opteron systems**
 - X86-64 architecture, enhancements over IA32
 - one path to memory per CPU
 - 8-CPU SMPs with hardly any external hardware



- CFD: Solving $\mathbf{A} \mathbf{x} = \mathbf{b}$
for finite volume methods can be done by Strongly-Implicit-Procedure (SIP) according to Stone
- SIP-solver is widely used:
 - LESOCC, FASTEST, FLOWSI (**Institute of Fluid Mechanics, Erlangen**)
 - STHAMAS3D (**Crystal Growth Laboratory, Erlangen**)
 - CADiP (**Theoretical Thermodynamics and Transport Processes, Bayreuth**)
 - ...
- SIP-Solver: 1) Incomplete LU-factorization
2) Series of forward/backward substitutions
- Toy program available at: <ftp.springer.de> in /pub/technik/peric (M. Peric)

SIP-solver Data dependencies & Implementations



Basic data dependency: $(i, j, k) \leftarrow \{(i-1, j, k); (i, j-1, k); (i, j, k-1)\}$

```
do k = 2 , kMax
  do j = 2 , jMax
    do i = 2 , iMax
      RES(i, j, k) = {RES(i, j, k) - LB(i, j, k) * RES(i, j, k-1)
$      - LW(i, j, k) * RES(i-1, j, k) - LS(i, j, k) * RES(i, j-1, k)
$      } * LP(i, j, k)
    enddo
  enddo
enddo
```

3-fold nested loop (3D): (i, j, k) Hyperplane: $(i+j+k=\text{const})$

- Data locality (Caches !)
- No shared memory parallelization (Hitachi: *Pipeline parallel processing*)
- Non-contiguous memory access
- vectorization of innermost loop
- unsuitable for RISC systems

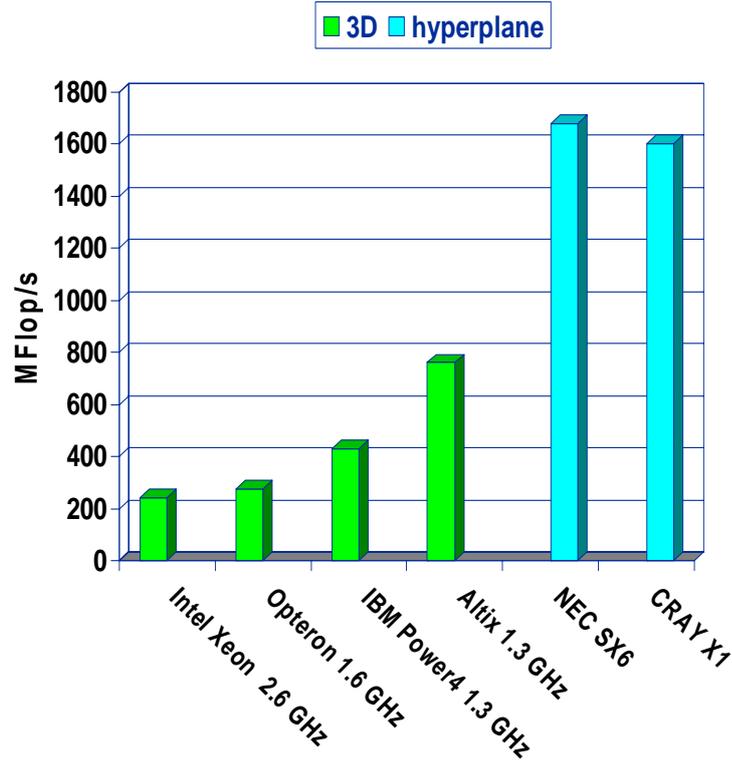
SIP-solver Basic Performance Numbers



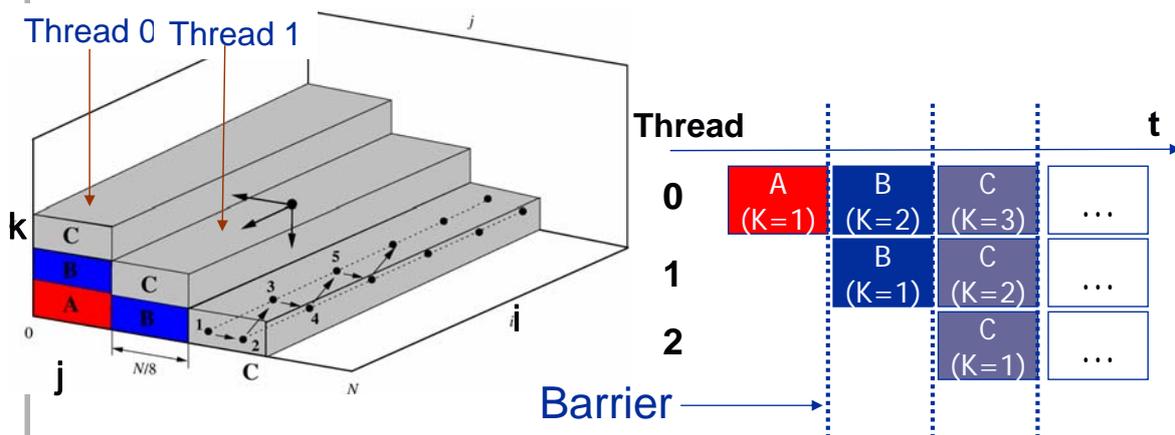
Benchmark

- Lattice: 91^3
- 100 MB
- 1 ILU
- 500 iterations

- X1: 1 MSP
- SX6: 1 CPU



SIP-solver Pipeline Parallel Processing



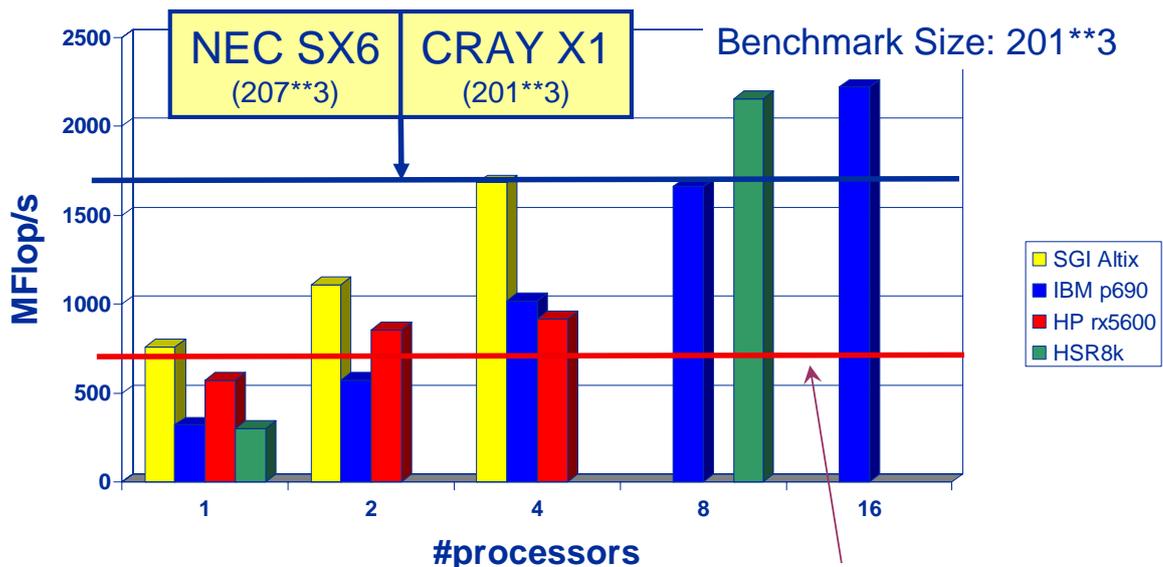
- Split up j -loop in chunks of equal size for each thread
- Split up k -direction in blocks of equal chunks
- Pipelining in k -direction: Only one k -Index is active at a fixed time
- Efficient parallelisation if $k_{Max}, j_{Max} \gg \#Threads$



```

$omp parallel private(...)
do l =2, kMax+numThreads-2,1
  threadID=OMP_GET_THREAD_NUM()
  k = l - threadID
  if((k.ge.2).and.(k.le.kMaxM)) then
    do j = jS(threadID),jE(threadID)
      do i = 2 , iMax
        RES(i,j,k) = {RES(i,j,k)-
$          LB(i,j,k)*RES(i,j,k-1) ... ! Same thread
$          ... LS(i,j,k)*RES(i,j-1,k) ...} ! threadID-1 in
          enddo ! in prev. l-iter
        enddo
      enddo
    endif
  $omp barrier
enddo
$omp end parallel
    
```

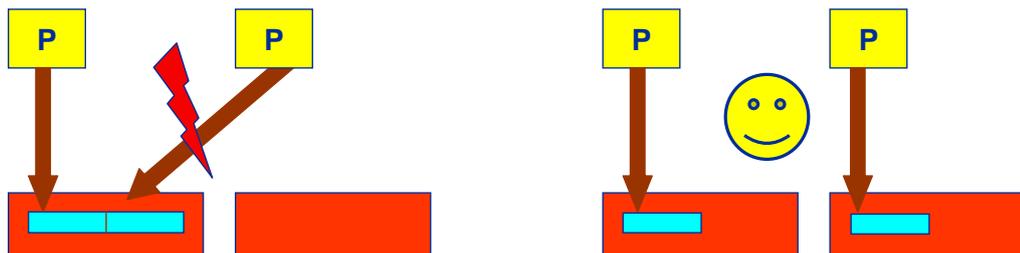
CFD kernel: SIP-solver SMP Performance vs. Vector CPUs



- IBM p690: speedup(16)=7
 - Hitachi SR8000: speedup(8)=7.2
 - HP rx5600: Intel Itanium2 – 1 GHz; one memory path!
- Altix 4-CPU starting point**



- Internode communication on Altix is significantly slower than intra-node (factor of 2 worse than Origin)
- Consequence: Data locality is even more important than on Origin
 - "First Touch" policy maps memory pages in the node where they are first used
 - Initialization of data structures must be parallelized to ensure proper placement!



- Change parallelization of initialization loop:

```

!$omp parallel do private(i,j)
do k=1,kMax
  do j=1,jMax
    do i=1,iMax
      T(i,j,k)=0.
    enddo
  enddo
enddo
    
```



```

do k=1,kMax
  !$omp parallel do private(i)
    do j=1,jMax
      do i=1,iMax
        T(i,j,k)=0.
      enddo
    enddo
  enddo
enddo
    
```





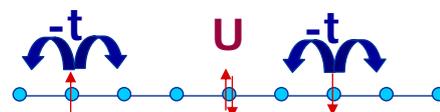
- **Density-Matrix Renormalization Group**
- Used in solid state physics and quantum chemistry to explore properties of low-lying states in quantum systems
- **Competing methods:** ED (Exact Diagonalization) and QMC (Quantum Monte Carlo)
- Especially compared to ED, many problems can be tackled on workstations instead of supercomputers
- **Goal: Parallelize / port existing C++ DMRG code to modern shared-memory systems**
- Use the parallelized code to push manageable physical system sizes (# of sites) to new heights

Motivation – Microscopic Models



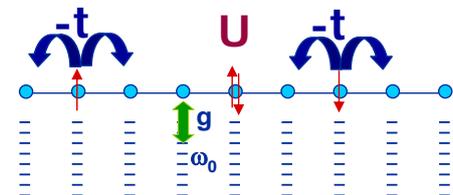
- **Microscopic Hamiltonians in second quantization**
e.g. Hubbard model

$$H = -t \sum_{\langle ij \rangle, \sigma} [c_{i\sigma}^\dagger c_{j\sigma} + \text{H.c.}] + U \sum_i n_{i\uparrow} n_{i\downarrow}$$



- e.g. Holstein-Hubbard model (HHM)

$$H = -t \sum_{\langle ij \rangle, \sigma} [c_{i\sigma}^\dagger c_{j\sigma} + \text{H.c.}] + U \sum_i n_{i\uparrow} n_{i\downarrow} + g\omega_0 \sum_{i,\sigma} (b_i^\dagger + b_i) n_{i\sigma} + \omega_0 \sum_i b_i^\dagger b_i$$



Hilbert space / #quantum states growth exponentially

HHM using an N-site lattice: $4^N * (M+1)^N$ (N~10-100; M~10)

Electrons Phonons: Max. M per Site



Traditional Approaches

- **Quantum Monte Carlo (QMC)**
- **Exact Diagonalization (ED):** Massively Parallel Codes on Supercomputers

New Approach

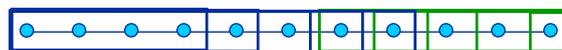
- **Density Matrix Renormalization Group (DMRG) Method**
 - Originally introduced by White in 1992
 - Large sequential C++ package is in wide use (quantum physics and quantum chemistry)
 - Elapsed Times: hours to weeks with desktop CPUs
 - No parallel implementation available to date

DMRG Algorithm



DMRG algorithm (finite size; left to right sweep)

1. Diagonalize reduced DM for a system block of size l and extract m eigenvectors with largest eigenvalue
2. Construct all relevant operators (system block & environment, ...) for a system block of size $l+1$ in the reduced density matrix eigenbasis
3. Form a superblock Hamiltonian from system & environment Hamiltonians plus two single sites
4. **Diagonalize new superblock Hamiltonian**



Accuracy depends mainly on m ($m \sim 100 - 10000$)



Implementation

- Start-Up with infinite-size algorithm
- DM diagonalization: LAPACK (dsyev) costs about 5 %
- **Superblock diagonalization costs about 90 % (Davidson algorithm)**
- **Most time-consuming step: Sparse matrix-vector multiply (MVM) in Davidson (costs about 85 %)**
- **Sparse matrix H is constructed by the transformations of each operator in H :**

$$H_{ij;i'j'} = \sum_{\alpha} A_{ii'}^{\alpha} B_{jj'}^{\alpha}$$

Contribution from system block and from environment

DMRG Algorithm: Parallelization



Implementation of sparse MVM

- **Sparse MVM: Sum over dense matrix-matrix multiplies!**

$$\sum_{i'j'} H_{ij;i'j'} \psi_{i'j'} = \sum_{\alpha} \sum_{i'} A_{ii'}^{\alpha} \sum_{j'} B_{jj'}^{\alpha} \psi_{i'j'}$$

- **However A and B may contain only a few nonzero elements, e.g. if conservation laws (quantum numbers) have to be obeyed**

- **To minimize overhead an additional loop (running over nonzero blocks only) is introduced**

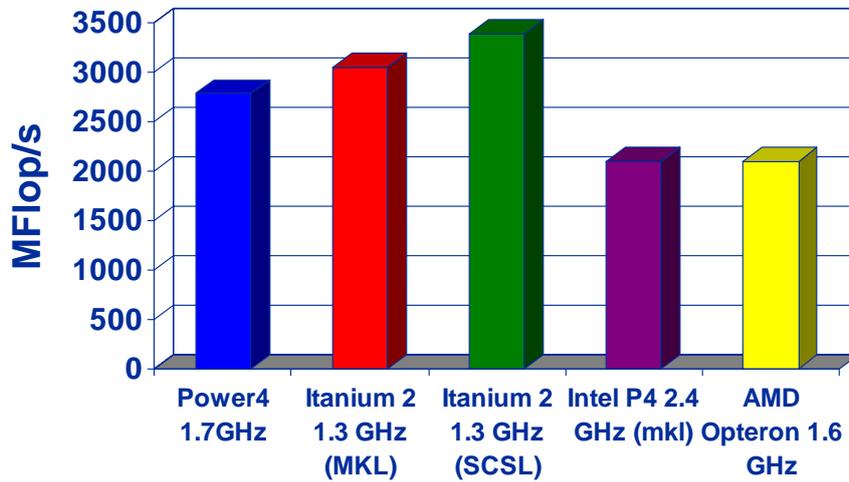
$$\begin{aligned} H\psi &= \sum_{\alpha} \sum_k (H\psi)_{L(k)}^{\alpha} \\ &= \sum_{\alpha} \sum_k A_k^{\alpha} \psi_{R(k)} [B^T]_k^{\alpha} \end{aligned}$$

- **Dense matrix-matrix multiplies are implemented using DGEMM from BLAS**

DMRG Serial Performance



- DGEMM core leads to a significant fraction of peak for real-life problems
- Itanium 2 is competitive with respect to Power4
- Choice on Altix: Use **MKL** or **SCSL**?
- DMRG performs better with **SCSL**!

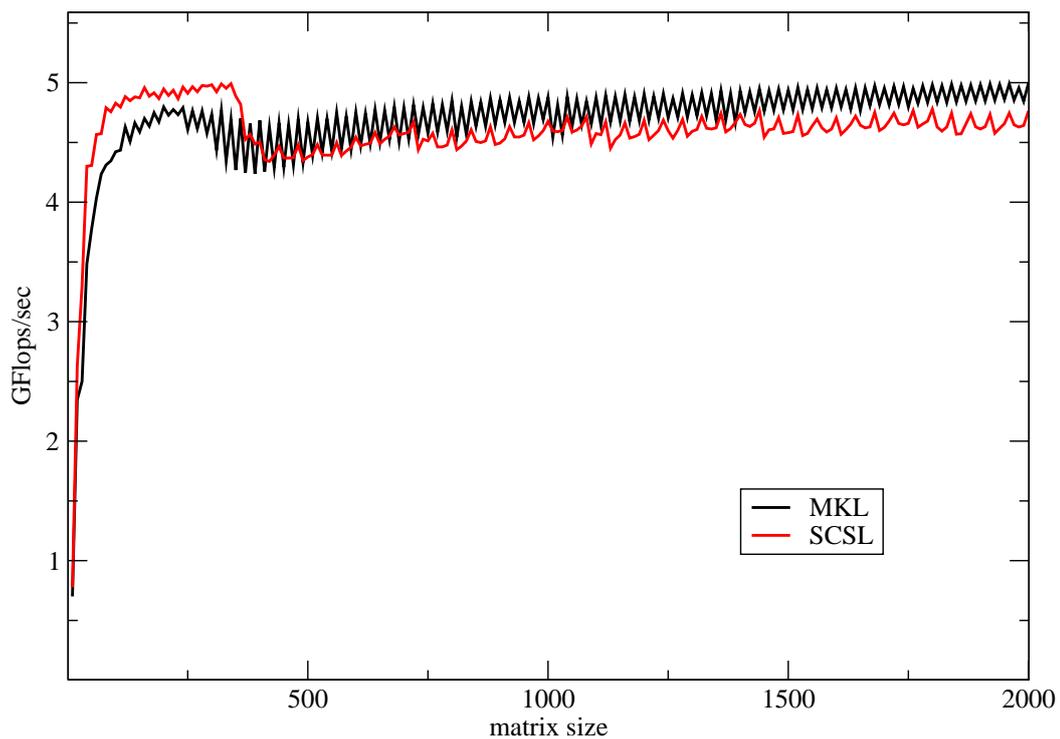


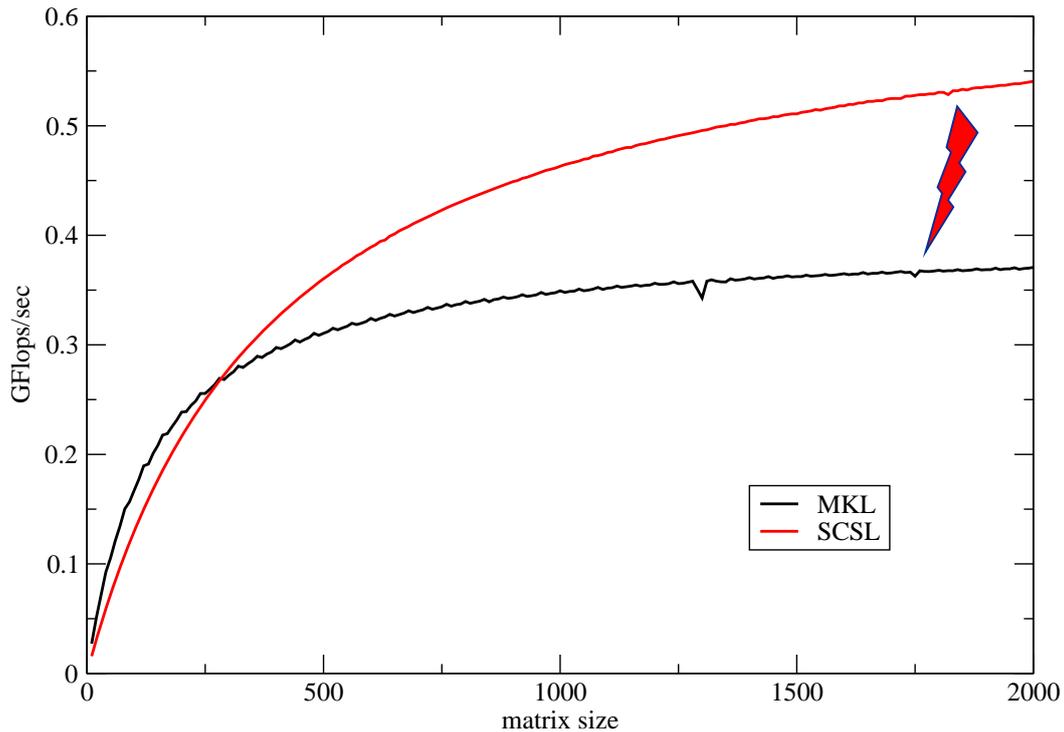
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georg.hager@rrze.uni-erlangen.de

Altix Performance

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20C

DMRG: Potential Parallelization approaches



1. Linking with parallel BLAS (DGEMM)

- Does not require restructuring of code
- Significant speedup only for large (transformation) matrices (A , B)

2. Shared-Memory parallelization of outer loops

- Chose **OpenMP** for portability reasons
- Requires some restructuring & directives
- Speedup should not depend on size of (transformation) matrices

Maximum speedup for total program:

- if MVM (accounts for 85%) is parallelized only: ~6 - 8

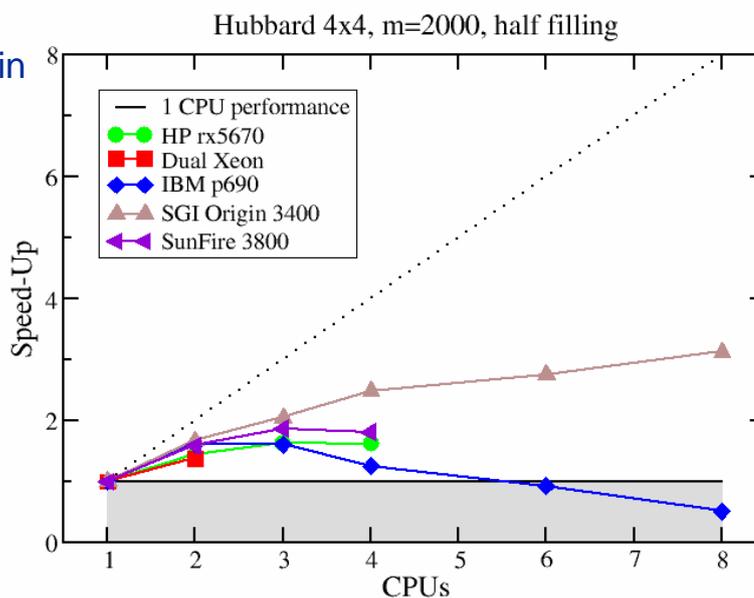
MPI parallelization

- Requires complete restructuring of algorithm -> new code



Linking with parallel BLAS

- Useless on IBM for #CPU > 4
- Best scalability on Origin (Network, BLAS implementation)
- Dual processor nodes can reduce elapsed runtime by about 30 %
- Increasing m to 7000: $S(4) = 3,2$ (SGI & HP)
- Small m (~600) with HHM: No Speed-Up

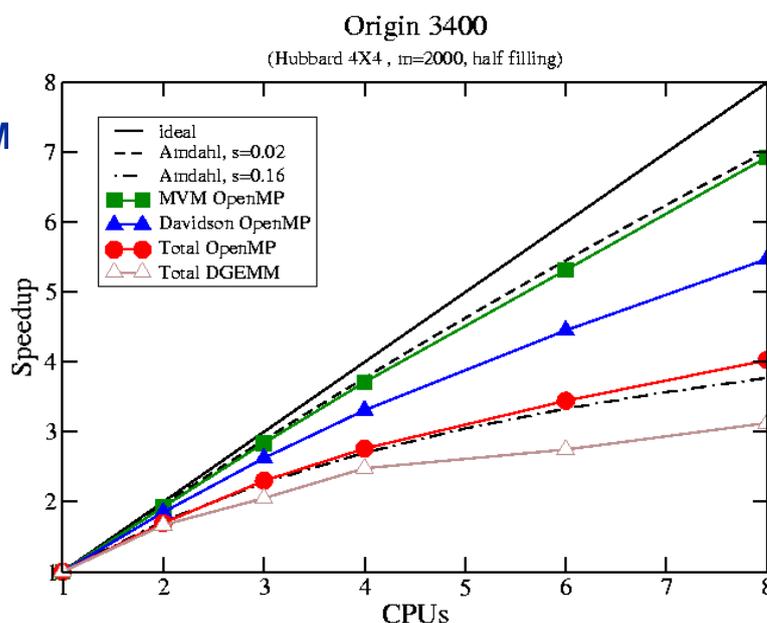


DMRG: OpenMP Parallelization



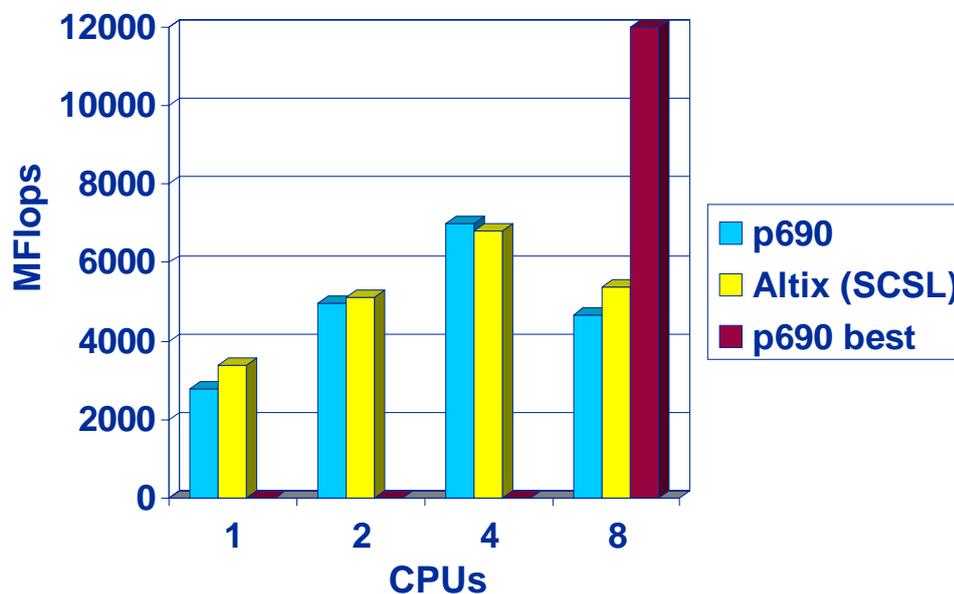
Scalability on Origin

- OpenMP scales significantly better than parallel DGEMM
- Serial overhead in parallel MVM is only about 2%!
- Linking with parallel BLAS gives an additional performance gain of 15 %!





- Comparison of DMRG scalability

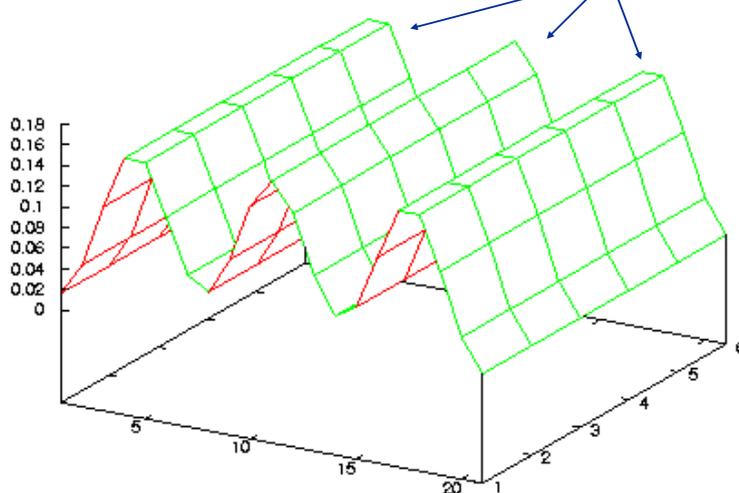


Application: Ground State of 21x6 (OpenxPeriodic) BCs Hubbard ladder with 12 holes



Hole density at $m=6000$, $U=12$

3 stripes!



Previously possible only with up to 7x6 sites!



- G. Hager, E. Jeckelmann, H. Fehske, and G. Wellein: *Parallelization Strategies for Density Matrix Renormalization Group Algorithms on Shared-Memory Systems*.
J. Comp. Phys. 194, 795 (2004)
- G. Hager, E. Jeckelmann, H. Fehske, and G. Wellein: *Exact Numerical Treatment of Finite Quantum Systems using Leading-Edge Supercomputers*.
To be published in: *Proceedings of the International Conference on High Performance Scientific Computing*, March 10-14 2003, Hanoi, Vietnam (Springer)
- G. Hager, E. Jeckelmann, H. Fehske, and G. Wellein: *Investigation of Stripe Formation in Hubbard Ladders using parallel DMRG*
To be published in: *High Performance Computing in Science and Engineering Munich 2004*, March 2-3 2004, Munich, Germany (Springer)



- **Memory placement is very important on Altix**
 - initialize data structures the way they are accessed later
 - does not seem to be that much of a problem with p690
- **SCSL is worth a look as an alternative to MKL**
 - MKL is getting better
 - "nested parallelism" issues with MKL
- **OpenMP scalability problems on Altix**
 - Hope for compiler improvements?
 - p690 suffers from similar symptoms, but the cause is different
- **Altix outperforms p690 for CFD Codes**