

Firedrake: a multilevel domain specific language approach to unstructured mesh stencil computations

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Introduction

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Exploiting structure

Benchmarking

Conclusions

What are we interested in?

- ▶ (Predominantly) finite element simulations
 - ▶ primary application areas in geophysical fluids (ocean and atmosphere)
 - ▶ simulations on unstructured and semi-structured meshes
- ▶ Providing high-level interfaces for users, with performance

What are we interested in?

- ▶ (Predominantly) finite element simulations
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 - ▶ simulations on unstructured and semi-structured meshes
- ▶ Providing high-level interfaces for users, with performance
- ▶ the moon, on a stick

What are the elementary operations?

- ▶ **Numerics** tell us the elementary operation we apply everywhere in the mesh (a "kernel")
- ▶ **Mesh topology** gives us the "stencil" pattern
- ▶ Our job: efficiently apply the kernel over the whole mesh



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Maintaining abstractions

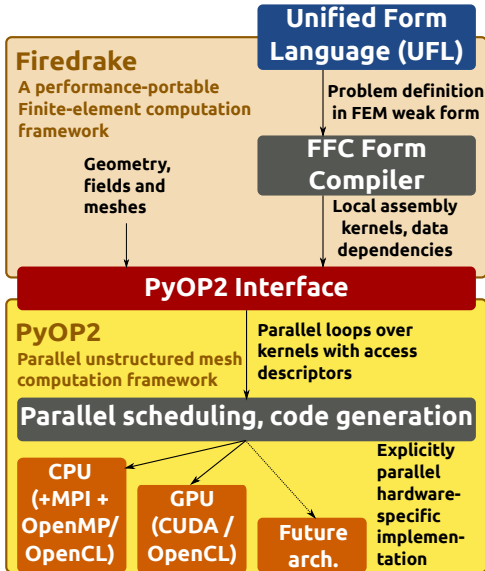
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Express what, not how

- ▶ User code should make as few decisions about implementation as possible
- ▶ FE discretisations expressed symbolically using the **Unified Form Language**
 - ▶ developed in the FEniCS project (<http://www.fenicsproject.org>)
 - ▶ symbolic representation compiled to a C kernel
- ▶ Data to feed to kernel (and interface to solvers) provided by Firedrake (<http://www.firedrakeproject.org>)
- ▶ Execution of kernel over entire domain expressed as parallel loop with access descriptors
 - ▶ uses PyOP2 unstructured mesh library (<http://github.com/OP2/PyOP2>)



An example

```
from firedrake import *
m = UnitSquareMesh(32, 32)
V = FunctionSpace(m, 'Lagrange', 2)
u = Function(V)
v = TestFunction(V)
#  $F(u; v) = \int \nabla u \cdot \nabla v + uv dx$ 
F = inner(grad(u), grad(v))*dx + u*v*dx
solve(F == 0, u)
```

- ▶ Kernels produced for residual and jacobian evaluation
 - ▶ jacobian computed by symbolic differentiation of residual form
- ▶ Kernels executed over mesh using PyOP2
 - ▶ <http://github.com/OP2/PyOP2>

PyOP2 data model

- ▶ Data types

 - Set** e.g. cells, degrees of freedom (dofs)

 - Dat** data defined on a Set (one entry per set element)

 - Map** a mapping between two sets (e.g. cells to dofs), a "stencil"

 - Global** global data (one entry)

 - Kernel** a piece of code to execute over the mesh (in C)

- ▶ access descriptors

 - ▶ READ, RW, WRITE, INC, ...

- ▶ iteration construct

 - par_loop** execute a Kernel over every element in a Set

Example

```
elements = Set(...)
nodes = Set(...)
elem_node = Map(elements, nodes, 3, ...) # 3 nodes per element
node_data = Dat(nodes, ...)
element_data = Dat(elements, ...)
count = Global(...) # no set (global value)
par_loop(kernel, elements,
         element_data(READ), # direct read
         node_data(INC, elem_node), # indirect increment
         count(INC)) # global increment
```

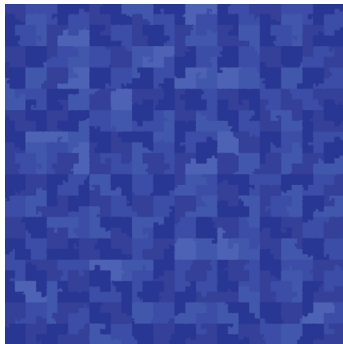
- ▶ executes **kernel** for each **ele** in **elements**
- ▶ runtime knows it has to care about data dependencies for
 - ▶ increments into **node_data**
 - ▶ increment into **count**

Synthesis, not analysis

- ▶ Low level code is generated at runtime for parallel loops
- ▶ Access descriptors on parallel loops mean:
 - ▶ code generation requires synthesis, not analysis
 - ▶ determination of when halo exchanges need to occur is automatic
 - ▶ colouring for shared memory parallelisation can be computed automatically

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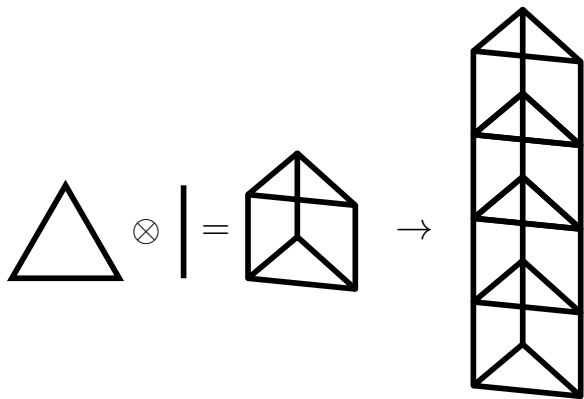
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Semi-structured meshes

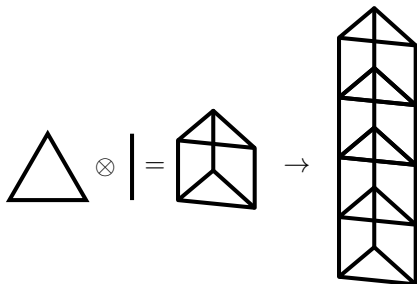
- ▶ Many application areas have a "short" direction
 - ▶ ocean and atmosphere
 - ▶ thin shells
- ▶ Numerics dictate we should do something different in short direction
- ▶ Use semi-structured meshes
 - ▶ unstructured in "long" directions, structured in short
 - ▶ can we exploit this structure?

A picture of triangles



Admits a fast implementation

- ▶ Exploit structure in mesh to amortize indirect lookups
 - ▶ arrange for iteration over short direction to be innermost loop
 - ▶ pay one indirect lookup per mesh column
 - ▶ walk up column directly



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A bandwidth bound test

- ▶ Walk over mesh, read from vertices and cells, sum into global

```
void kernel(double *a, double *x[], double *y[]) {  
    const double area = fabs(x[0][0]*(x[2][1]-x[4][1])  
                             + x[2][0]*(x[4][1]-x[0][1])  
                             + x[4][0]*(x[0][1]-x[2][1]));  
    *a += area * 0.5 * y[0][0];  
}
```

- ▶ Can we sustain an appreciable fraction of memory bandwidth?

Measuring throughput

- ▶ "Effective" data volume
 - ▶ assume every piece of data is touched exactly once (in perfect order)
 - ▶ don't count data movement for indirection maps
- ▶ "Valuable" bandwidth
 - ▶ effective data volume per second
- ▶ Actual memory bandwidth will be higher (reading indirection maps)
 - ▶ but this is not "useful"

Benchmark setup

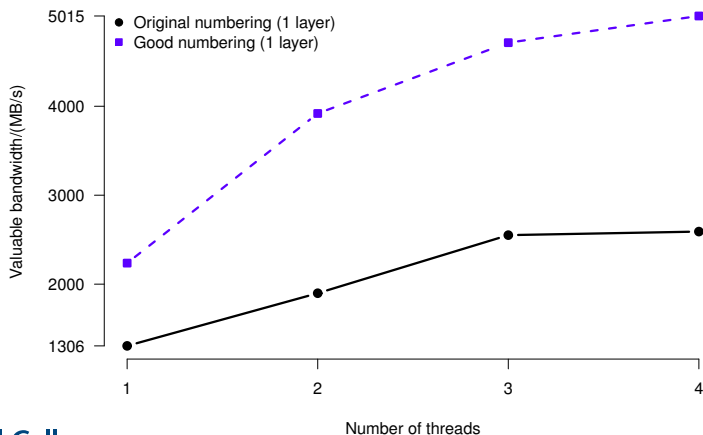
- ▶ 2D unstructured mesh: 806110 cells, 403811 vertices.
 - ▶ 2D coordinate field located at vertices (implicit 3rd coordinate)
 - ▶ scalar field stored at cell centres
- ▶ Run with increasing number of extruded cell layers (n_{layer})
 - ▶ data volume $(806110 * n_{\text{layer}}) + 403811 * 2 (n_{\text{layer}} + 1)$ doubles
 - ▶ 1 layer: 18.4MB
 - ▶ 200 layers: 2468MB
- ▶ Execute kernel over mesh 100 times

Single node

- ▶ Intel Sandybridge 4 cores (2 way hyperthreading)
 - ▶ 32kB L1 cache (per core)
 - ▶ 256 kB L2 cache (per core)
 - ▶ 8 MB L3 cache (shared)
- ▶ Measured STREAM bandwidth (8 threads)
 - ▶ 11341 MB/s

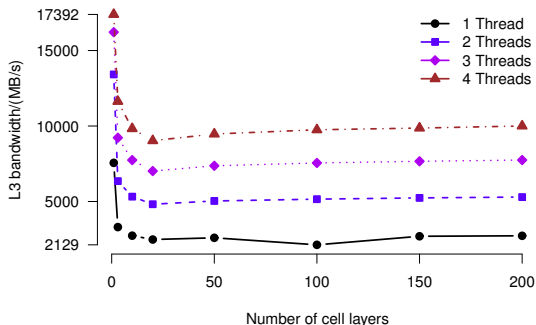
Effect of good base numbering

- ▶ Being completely unstructured hurts a lot
- ▶ Compare default (mesh generator) numbering with renumbered mesh using 2D space filling curve



Adding layers amortizes indirection cost

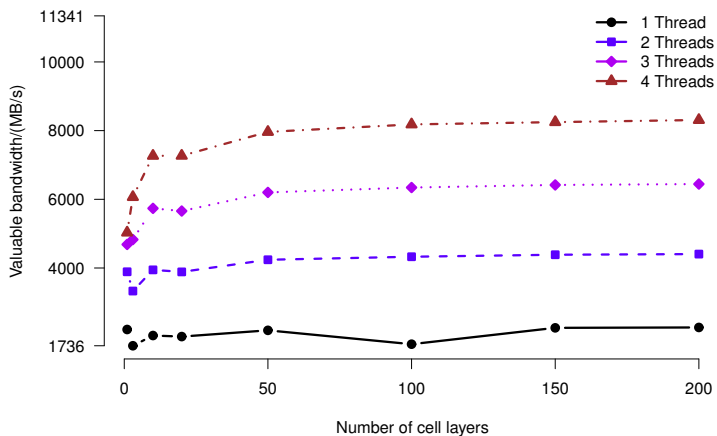
- ▶ L3 cache bandwidth
 - ▶ low layer numbers hit the L3 more often (indirection lookups)



- ▶ What about actual throughput though?

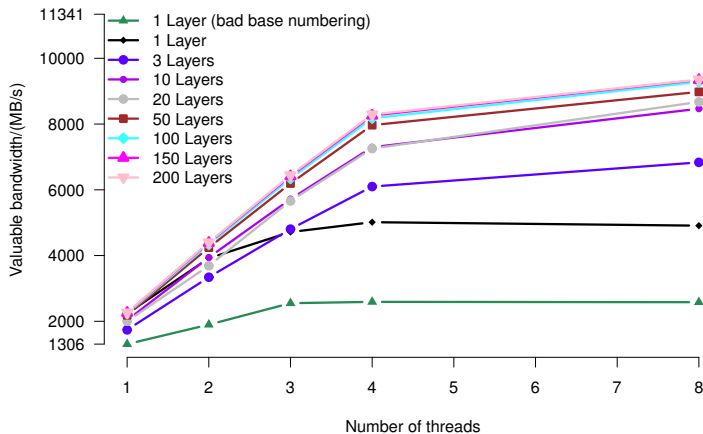
Valuable bandwidth

- Above ~ 20 layers, indirection cost "hidden"



More threads

- ▶ Hypertreading gives some further gains (82% STREAM bandwidth)



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Possible to be unstructured and fast

- ▶ A good numbering gets you a reasonable way there
- ▶ If there is structure in your problem, use it!
- ▶ High level abstractions need not kill performance

- ▶ All code is open source, and online:
 - Firedrake <http://www.firedrakeproject.org> and <http://github.com/firedrakeproject/firedrake>
 - PyOP2 <http://github.com/OP2/PyOP2>
(documentation at <http://op2.github.io/PyOP2>)
- ▶ Postdoc positions in this area are available
 - ▶ contact: me (lawrence.mitchell@imperial.ac.uk) or David Ham (david.ham@imperial.ac.uk)

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