

Efficient Large-Scale Sparse Eigenvalue Computations on Heterogeneous Hardware

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Density of states

Key step: Computation of Chebyshev polynomials

Kernel Polynomial Method[1] for DOS:

```

for r = 0 to R-1
  |v> = |rand();
  Compute η0, η1
  for m = 1 to M/2
    swap(|w>, |v>);
    |u> = H|v>;
    |u> = |u> - b|v>;
    |w> = -|u>;
    |w> = |w> + 2a|u>;
    η2m = <v|v>;
    η2m+1 = <w|v>;
  end
end
  
```

← Loop: random initial states
 ← Loop: Chebyshev polynomials
 ← Sparse matrix-vector multiply
 ← Vector-vector operations
 ← Compute moments

Bandwidth-bound algorithm
 → Increase computational intensity I:

1. Fuse vector-vector operations into SpMV: **augmented SpMV**
2. Apply matrix to block of R random vectors[6]: **augmented SpMMV**

```

|V> := |v>0..R-1;
|W> := |w>0..R-1;
|V> = |rand();
Compute η0, η1
for m = 1 to M/2
  swap(|W>, |V>);
  |W> = 2a(H-b)|V> - |W> &
  η2m = <V|V> &
  η2m+1 = <W|V>
end
  
```

→ Higher performance
 → Custom implementation
 → Interleaved storage of block vectors

→ New bottlenecks!?

Motivation

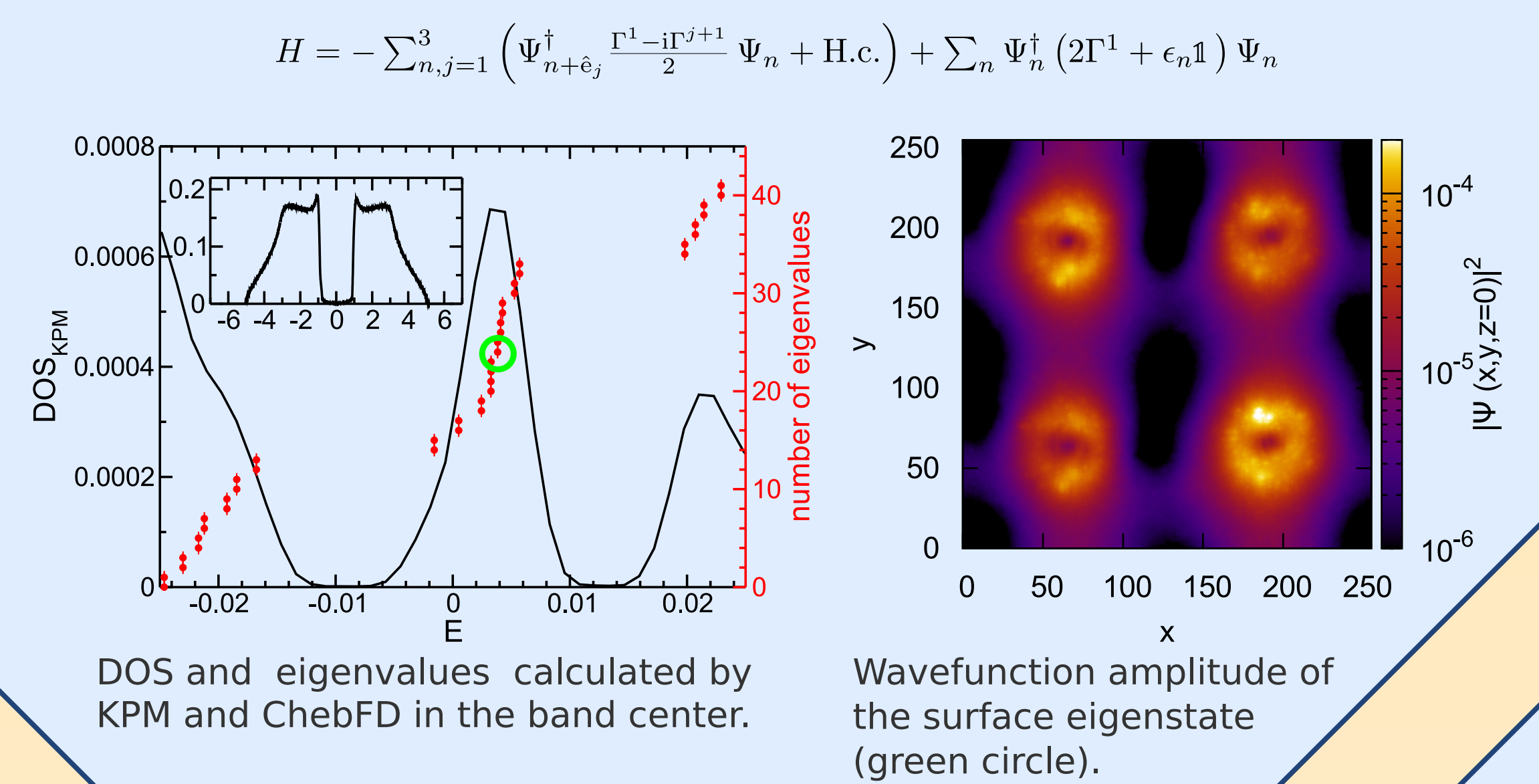
Goal: Determine eigenvalue properties of large, sparse matrix (H)

$$Hx = \lambda x, \quad \lambda_1, \lambda_2, \dots, \lambda_k, \dots, \lambda_{D-1}, \lambda_D$$

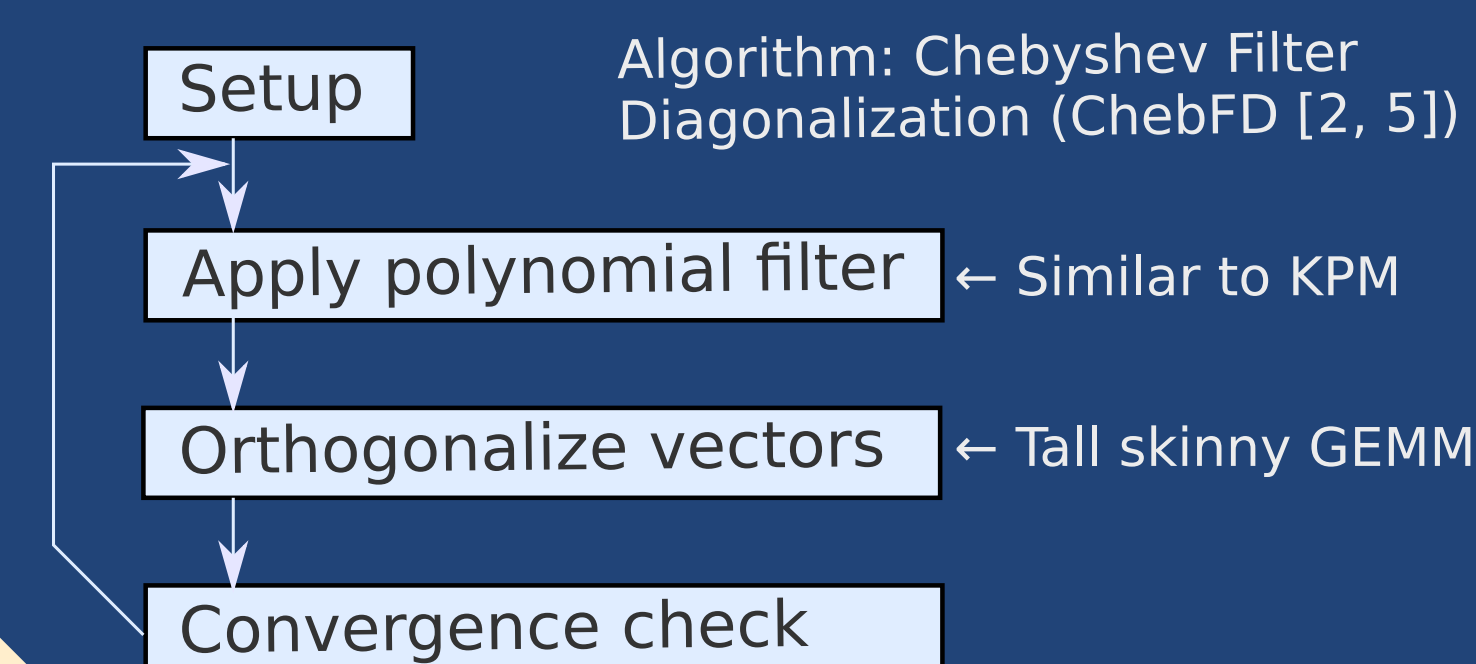
- Target features:
- Density of states (DOS)
Approximation to the full eigenvalue spectrum
 - Inner eigenvalues ($10^2, \dots, 10^3$)
 - Matrix dimension $D \geq 10^9$
- Efficient and scalable
 Fully heterogeneous (CPU+GPU) implementation

Physics application

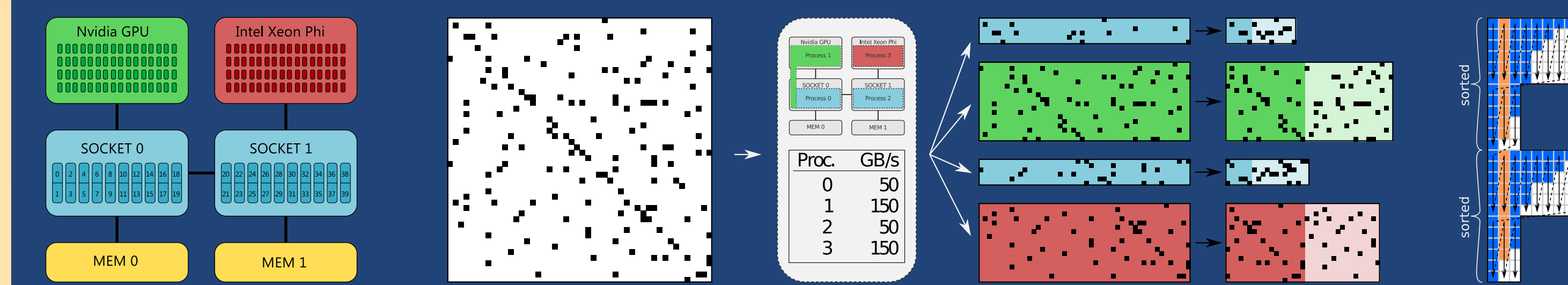
Gate-defined quantum dots on topological insulator surfaces



Inner Eigenvalues



Implementation



Fully heterogeneous execution with GHOST[4]:

- Data-parallel heterogeneous execution
- Fused and auto-generated kernels
- SELL-C-σ sparse matrix storage format
- MPI+OpenMP+CUDA+SIMD+Tasking

Download



bitbucket.org/essex

Performance: Roofline model

Topological insulator matrix:
 # non-zeros per row $N_{nzr} = 13$

- I = 0.29 F/B
↓ Fused Kernel
- I = 0.45 F/B
↓ Blocking ($R \rightarrow \infty$)
- I = 2.88 F/B

Computational intensity (finite R):
 $I(R) = 138 / [(260/R) + 48]$ F/B

Prediction[3] for bandwidth-bound code: $P_{MEM} = I * b_{MEM}$ ($b_{MEM} = \text{max. bandwidth}$)

Increasing R ↔ Limited cache size
 → Increased memory traffic

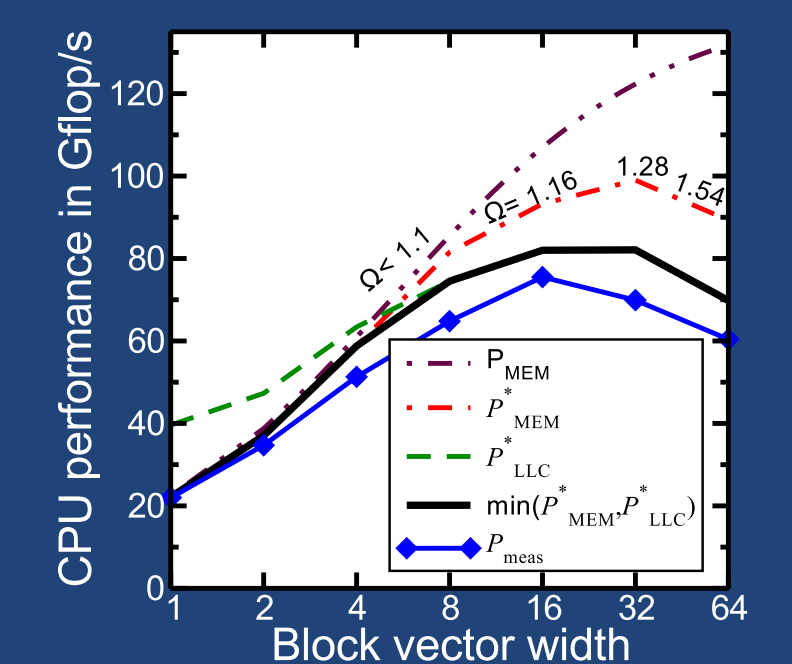
Ω = actual over minimum data volume

Corrected prediction: $P_{MEM}^* = \Omega P_{MEM}$

→ Decoupling from main memory

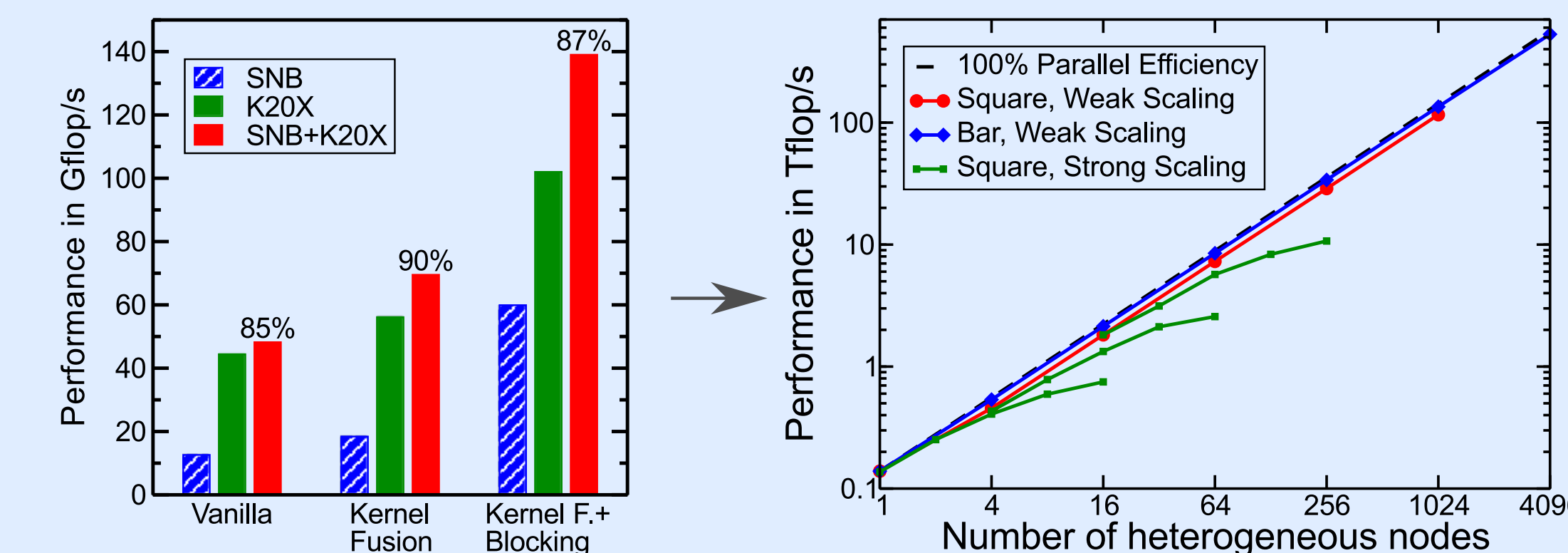
→ New CPU bottleneck: cache bandwidth b_{LLC}

→ New GPU bottleneck: reduction/synchronization for dot product

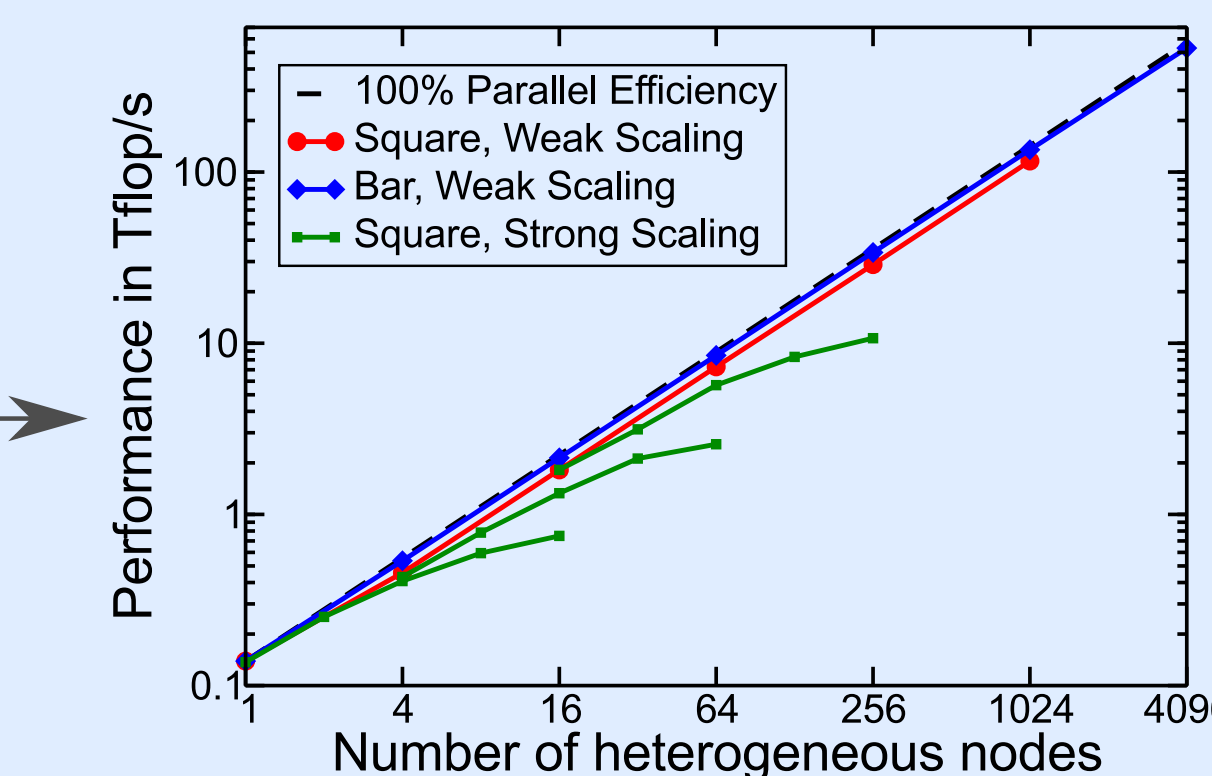


Performance

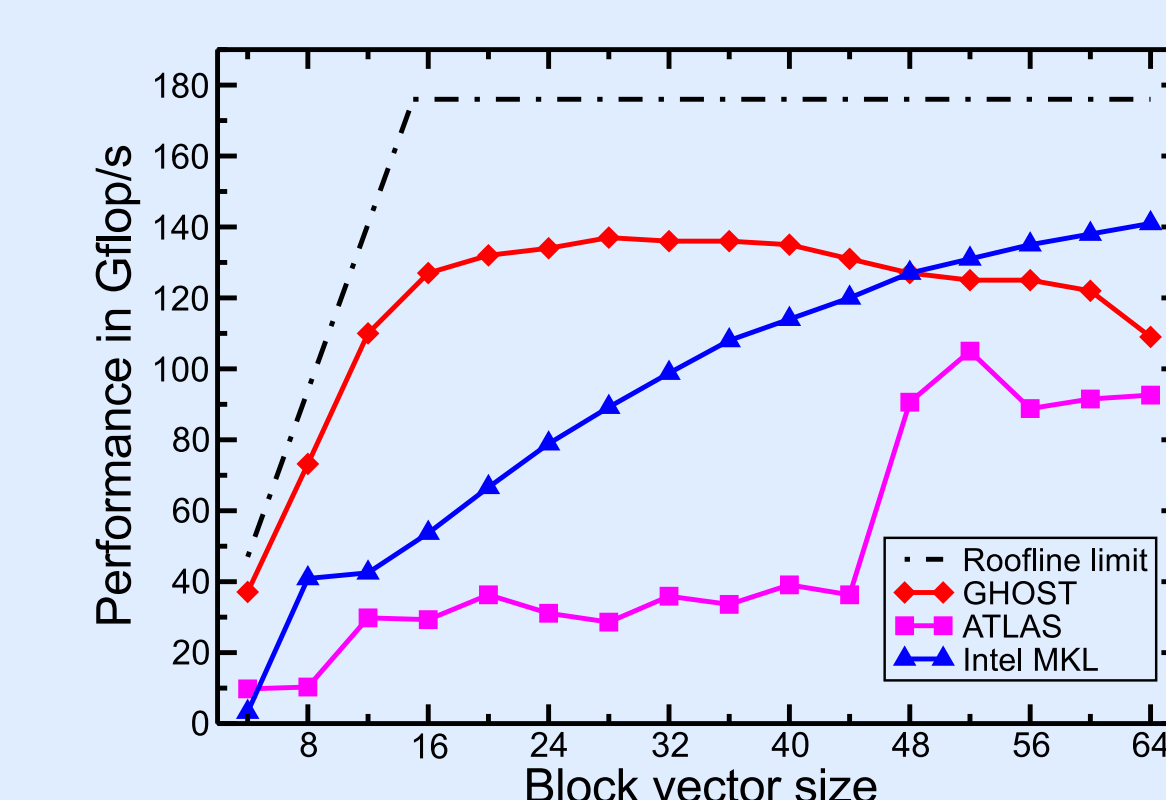
Optimized algorithm + tuned single-device implementations + fully heterogeneous execution



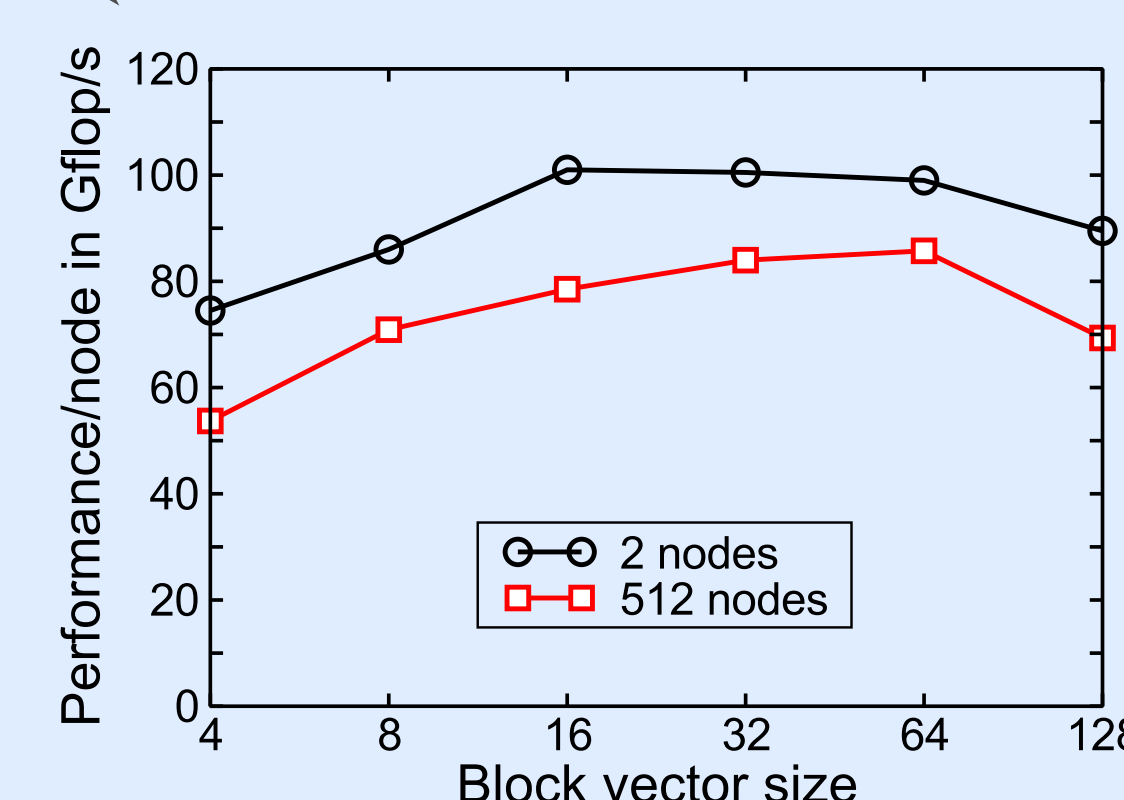
Node-level KPM performance on a single node of Piz Daint (1x Intel Xeon E5-2670, 1x Nvidia Tesla K20X).



Large-scale KPM performance (CPU+GPU) on Piz Daint (largest matrix $D=10^{10}$).



Block vector times small matrix performance on Intel Xeon E5-2660v2 (tall skinny ZGEMM).



Large-scale ChebFD performance (CPU) on SuperMUC Phase 2 (Intel Xeon E5-2697v3). On 512 nodes, 148 inner eigenvalues were sought of a matrix with $D=10^9$.

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References

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