

Analytical Tool-Supported Modeling of Streaming and Stencil Loops

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Scalable Tools Workshop

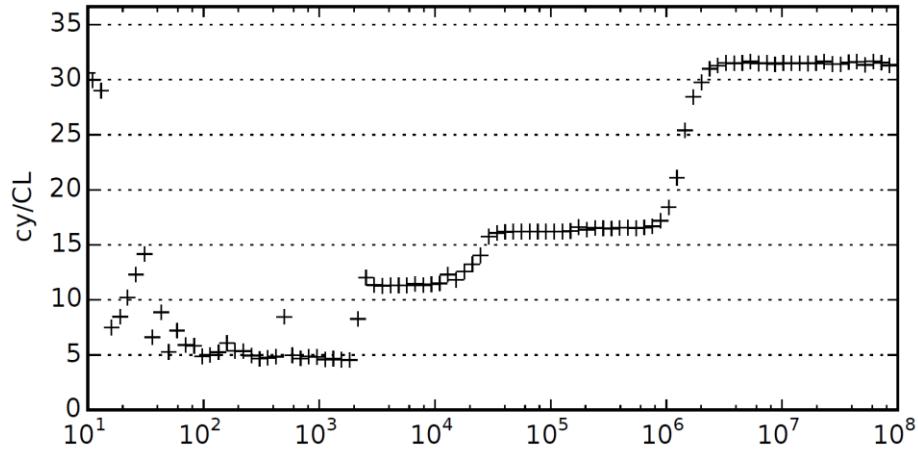
August 3-6, 2015, Lake Tahoe, CA

- LIKWID
tiny.cc/LIKWID
- GHOST
tiny.cc/GHOST
- Performance Engineering
[http://blogs.fau.de/...
hager/talks/nlpe](http://blogs.fau.de/hager/talks/nlpe)

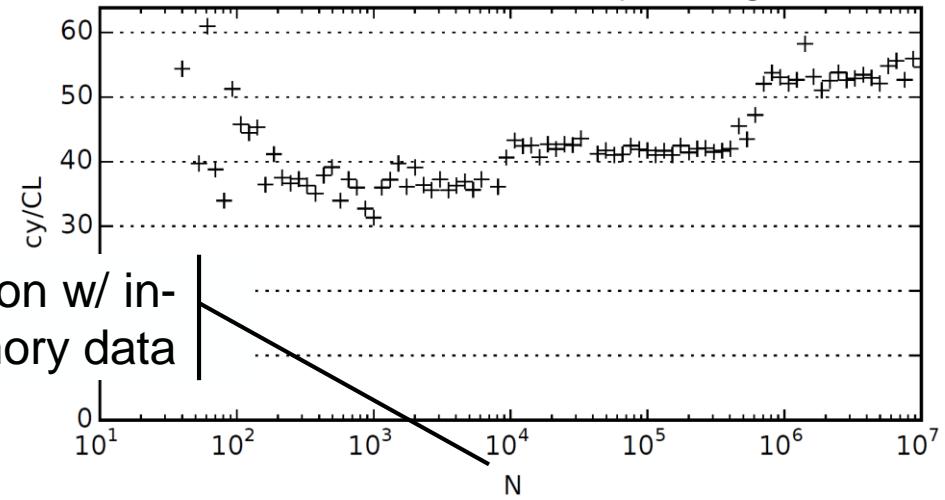


Motivation

DAXPY on Sandy Bridge core



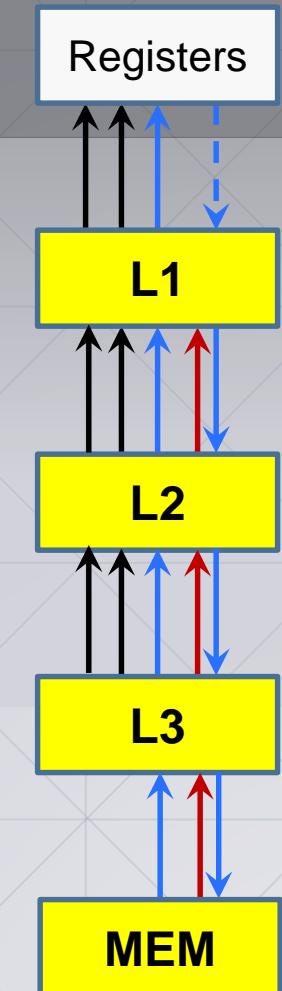
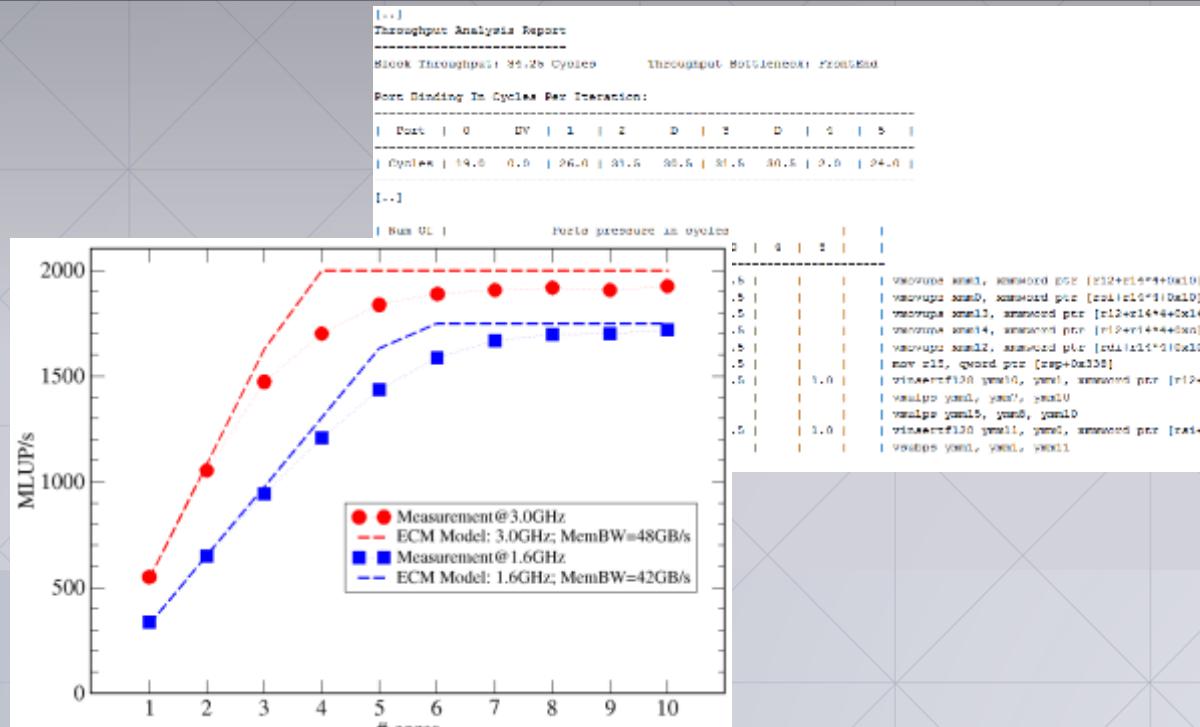
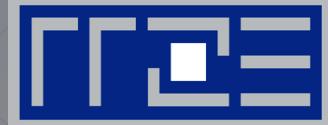
2D-5pt stencil on Sandy Bridge core



Loop length

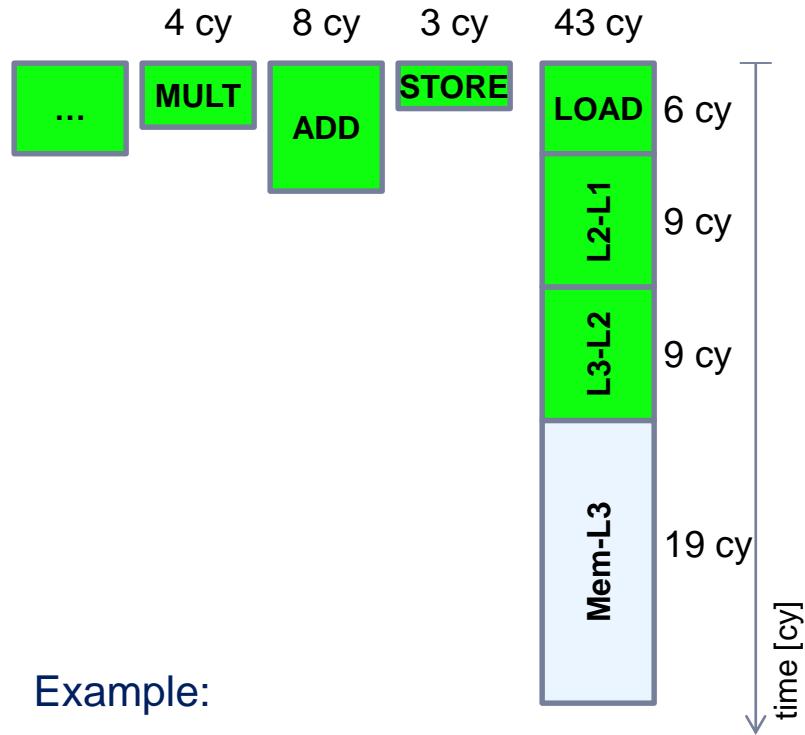
Inner dimension w/ in-
memory data

THE ECM MODEL



ECM model – the rules

1. LOADs in the L1 cache do not overlap with any other data transfer in the memory hierarchy
2. Everything else in the core overlaps perfectly with data transfers (STOREs show some non-overlap)
3. The scaling limit is set by the ratio of
$$\frac{\text{\# cycles per CL overall}}{\text{\# cycles per CL at the bottleneck}}$$



Example:

Single-core (data in L1): **8 cy** (ADD)

Single-core (data in memory):

$$6+9+9+19 \text{ cy} = \mathbf{43 \text{ cy}}$$

Scaling limit: $43 / 19 = 2.3$ cores

ECM model – composition

ECM predicted time

T_{ECM} = maximum of overlapping time and sum of all other contributions

$$T_{core} = \max(T_{nOL}, T_{OL})$$

$$T_{ECM} = \max(T_{nOL} + T_{data}, T_{OL})$$

Shorthand notation for time contributions:

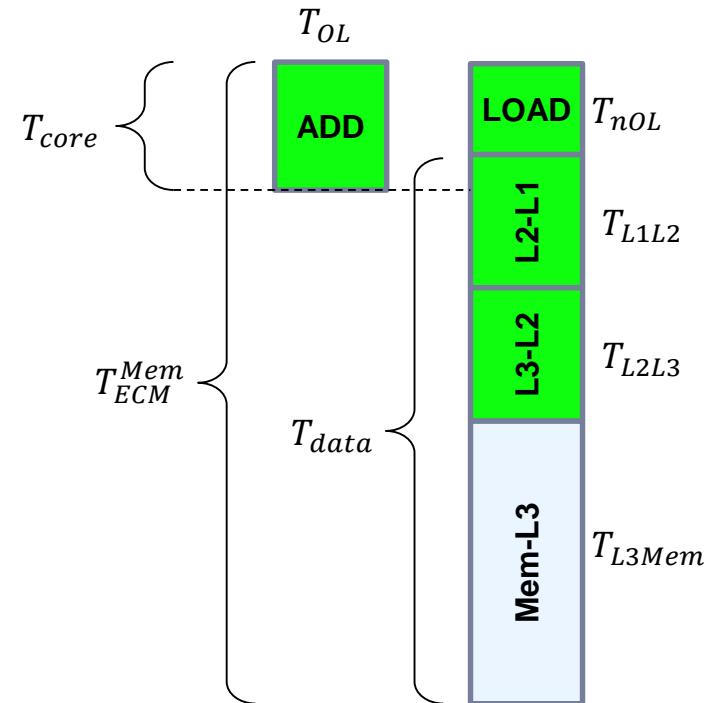
$$\{ T_{OL} \parallel T_{nOL} \mid T_{L1L2} \mid T_{L2L3} \mid T_{L3Mem} \}$$

$\underbrace{\hspace{10em}}$ $\underbrace{\hspace{10em}}$

cy invariant to
clock speed # cy changes w/
clock speed

Example from previous slide:

$$\{ 8 \parallel 6 \mid 9 \mid 9 \mid 19 \} \text{ cy}$$



ECM model – prediction

Notation for cycle predictions in different memory hierarchy levels:

$$\{ T_{ECM}^{L1} \mid T_{ECM}^{L2} \mid T_{ECM}^{L3} \mid T_{ECM}^{Mem} \}$$

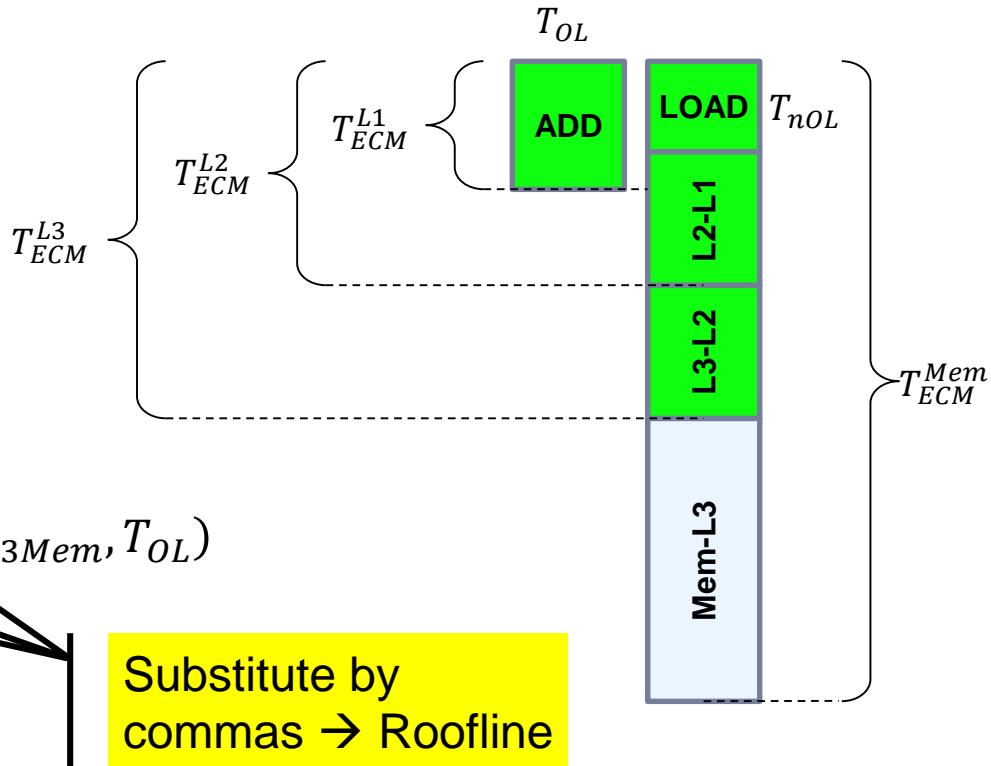
$$T_{ECM}^{L1} = T_{core} = \max(T_{nOL}, T_{OL})$$

$$T_{ECM}^{L2} = \max(T_{nOL} + T_{L1L2}, T_{OL})$$

$$T_{ECM}^{L3} = \max(T_{nOL} + T_{L1L2} + T_{L2L3}, T_{OL})$$

$$T_{ECM}^{Mem} = \max(T_{nOL} + T_{L1L2} + T_{L2L3} + T_{L3Mem}, T_{OL})$$

Example: { 8 | 15 | 24 | 43 } cy



Experimental data (measured) notation: 8.6 | 16.2 | 26 | 47 cy

ECM model – saturation

Main assumption: Performance scaling is linear until a bandwidth bottleneck (b_S) is hit

Performance vs. cores (Memory BN):

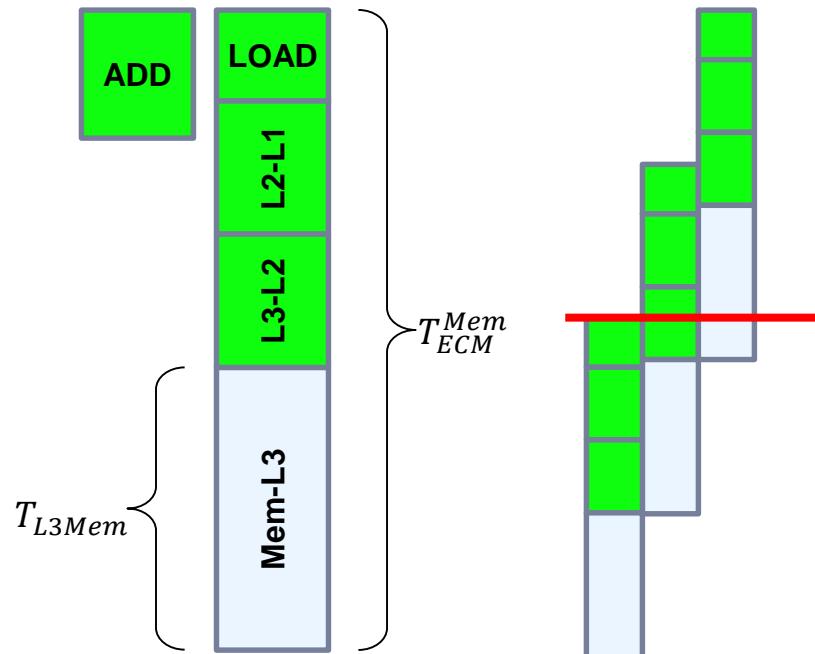
$$P_{ECM}(n) = \min\left(n P_{ECM}^{Mem}, \frac{b_S^{Mem}}{B_C^{Mem}}\right)$$

Number of cores at saturation:

$$n_S = \left\lceil \frac{b_S/B_C}{P_{ECM}^{Mem}} \right\rceil = \left\lceil \frac{T_{ECM}^{Mem}}{T_{L3Mem}} \right\rceil$$

Example:

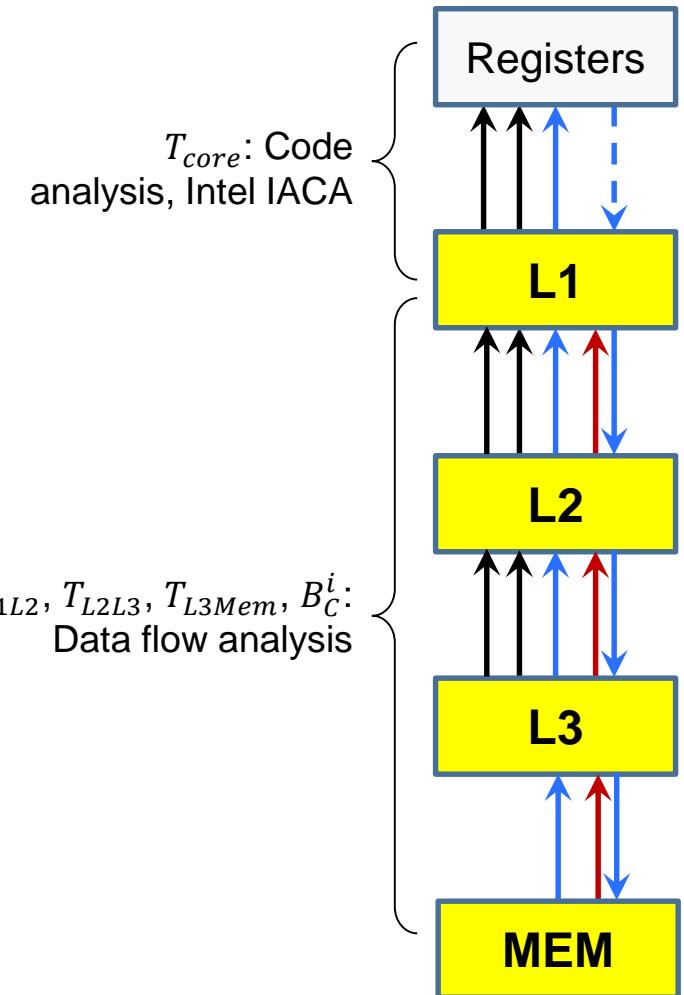
$$\{ 8 \| 6 | 9 | 9 | 19 \} \text{ cy}, \quad \{ 8] 15 | 24 | 43 \} \text{ cy} \Rightarrow n_S = \left\lceil \frac{43}{19} \right\rceil = 3$$



How do we get the numbers?

Basic information about hardware capabilities:

- In-core limitations
 - Throughput limits: μ ops, LD/ST, ADD/MULT per cycle
 - Pipeline depths
- Cache hierarchy
 - **ECM**: Cycles per CL transfer
 - **RL**: measured max bandwidths for all cache levels, core counts
- Memory interface
 - **ECM**: measured saturated BW
 - **RL**: measured max bandwidths for all core counts



2D 5-PT JACOBI STENCIL (DOUBLE PRECISION)

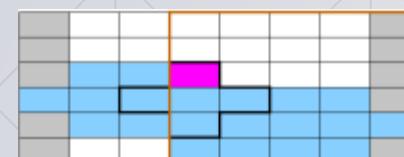
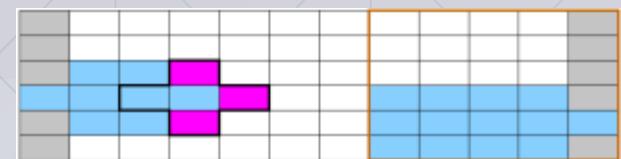


```
for(j=1; j < Nj-1; ++j)
  for(i=1; i < Ni-1; ++i)
    b[j][i] = (a[ j ][i-1] + a[ j ][i+1]
                + a[j-1][ i ] + a[j+1][ i ] ) * s;
```

Unit of work (1 CL): 8 LUPs

Data transfer per unit:

- 5 CL if layer condition violated in higher cache level
- 3 CL if layer condition satisfied



ECM Model for 2D Jacobi (AVX) on SNB 2.7 GHz

Radius- r stencil \rightarrow $(2r+1)$ layers have to fit

```
for(j=1; j < Nj-1; ++j)
  for(i=1; i < Ni-1; ++i)
    b[j][i] = (a[ j ][i-1] + a[ j ][i+1]
                + a[j-1][ i ] + a[j+1][ i ] ) * s;
```

Cache k has size C_k

Layer condition:

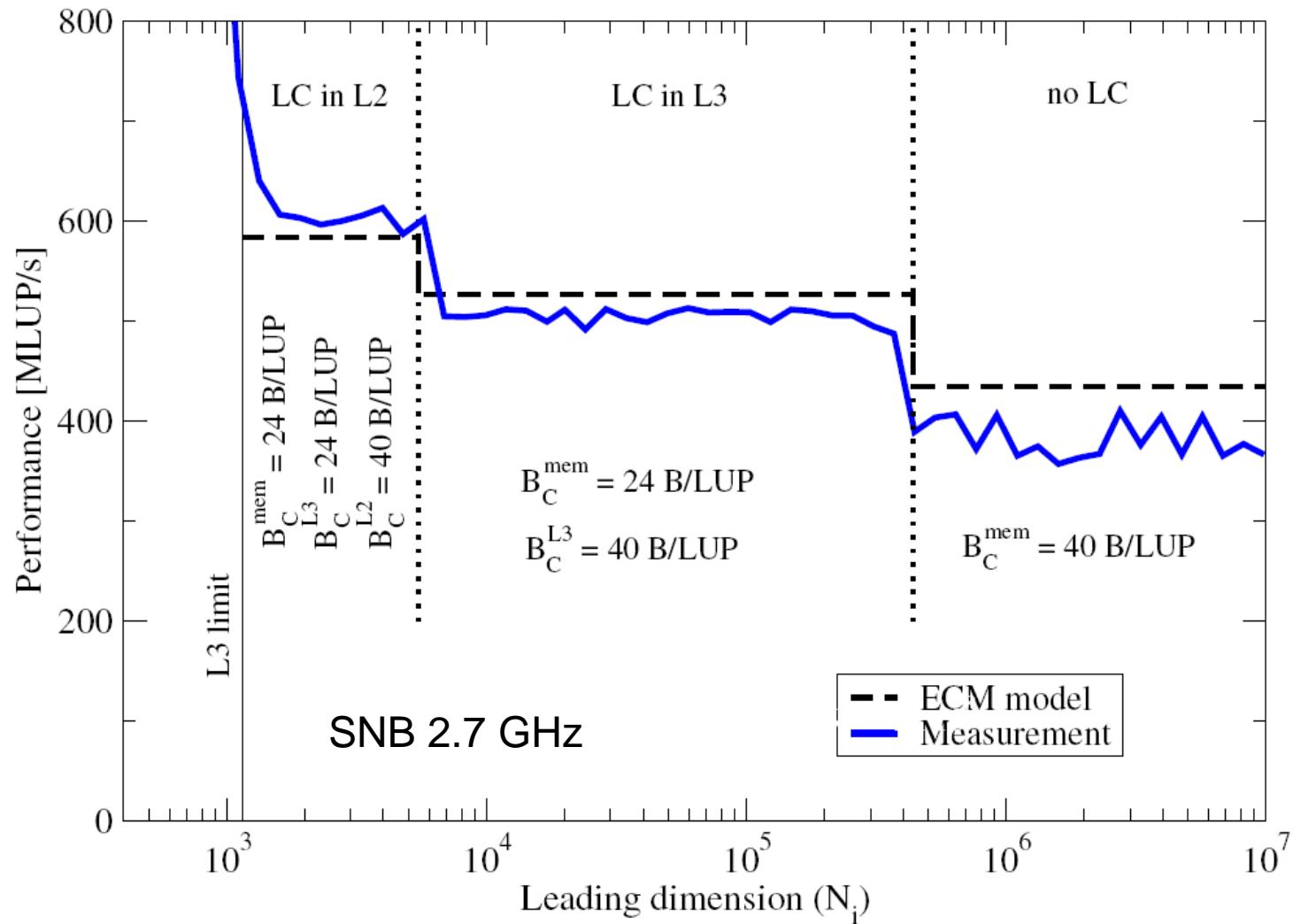
$$(2r + 1) \cdot N_i \cdot 8 B < \frac{C_k}{2}$$

2D 5-pt: $r = 1$

LC	ECM Model [cy]	prediction [cy]	$P_{\text{ECM}}^{\text{mem}}$ [MLUPS]	$N_i <$	n_S
L1	{6 8 6 6 13}	{8]14]20]33}	659	683	3
L2	{6 8 10 6 13}	{8]18]24]37}	587	5461	3
L3	{6 8 10 10 13}	{8]18]28]41}	529	436900	4
—	{6 8 10 10 22}	{8]18]28]50}	438	N/A	3

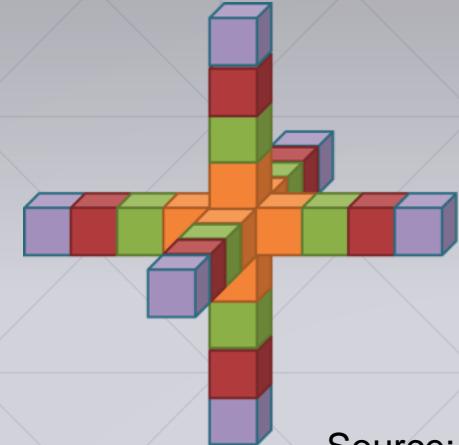
LC = layer condition satisfied in ...

2D 5-pt serial in-memory performance and layer conditions



3D LONG-RANGE STENCIL (SINGLE PRECISION)

```
#pragma omp parallel for
for(int k=4; k < N-4; k++) {
    for(int j=4; j < N-4; j++) {
        for(int i=4; i < N-4; i++) {
            float lap = c0 * %V%[k][j][i]
            + c1 * ( V[ k ][ j ][i+1]+ V[ k ][ j ][i-1])
            + c1 * ( V[ k ][j+1][ i ]+ V[ k ][j-1][ i ])
            + c1 * ( V[k+1][ j ][ i ]+ V[k-1][ j ][ i ])
            ...
            + c4 * ( V[ k ][ j ][i+4]+ V[ k ][ j ][i-4])
            + c4 * ( V[ k ][j+4][ i ]+ V[ k ][j-4][ i ])
            + c4 * ( V[k+4][ j ][ i ]+ V[k-4][ j ][ i ]);
            U[k][j][i] = 2.f * V[k][j][i] - U[k][j][i]
                        + ROC[k][j][i] * lap;
        }
    }
}
```



Source:
<http://goo.gl/dqOlnl>

3D long-range SP stencil ECM model

Layer condition in L3 at problem size $N_i \times N_j \times N_k$:

$$9 \cdot N_i \cdot b_j \cdot n_{threads} \cdot 4 B < \frac{C_3}{2}$$

ECM Model: { 68 || 62 | 24 | 24 | 17 } cy \rightarrow { 68 | 86 | 110 | 127 } cy

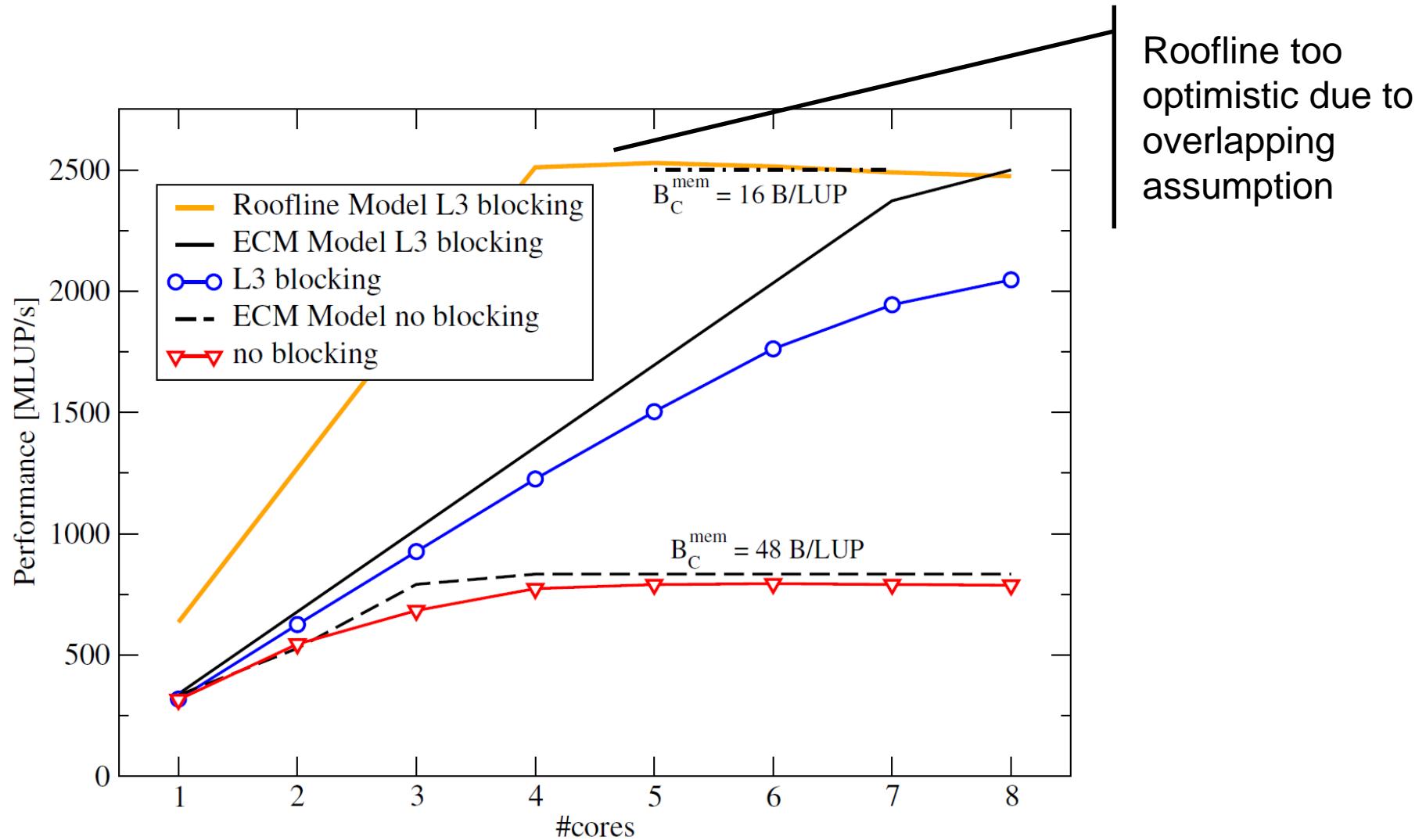
Saturation at $n_s = \left\lceil \frac{127}{17} \right\rceil = 8$ cores.

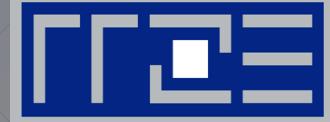
T_{L3Mem} plays minor part

Consequences:

- Temporal blocking will not yield substantial speedup
- Improve low-level code first (semi-stencil...?)

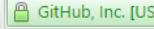
3D long-range SP stencil results (SNB)





First steps towards automated model construction

kerncraft: ECM/Roofline modeling toolkit

 GitHub, Inc. [US] <https://github.com/cod3monk/kerncraft>

GitHub This repository Search Explore Features Enterprise Blog

 cod3monk / **kerncraft**  Watch 1

kerncraft

Loop Kernel Analysis and Performance Modeling Toolkit

This tool allows automatic analysis of loop kernels using the Execution Cache Memory (ECM) model, the Roofline model and actual benchmarks. kerncraft provides a framework to investigate the data reuse and cache requirements by static code analysis. In combination with the Intel IACA tool kerncraft can give a good overview of both in-core and memory bottlenecks and use that data to apply performance models.

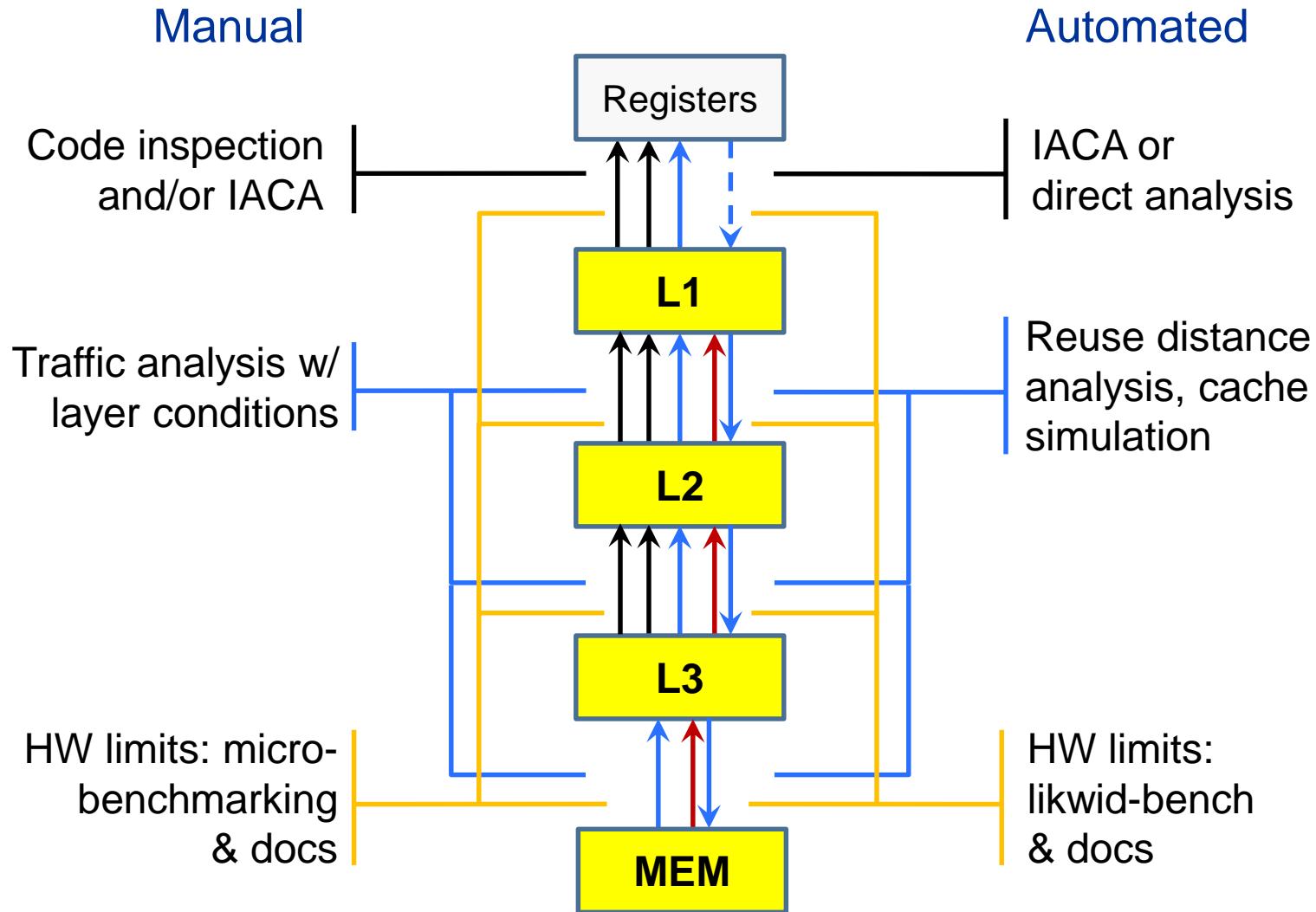
Installation

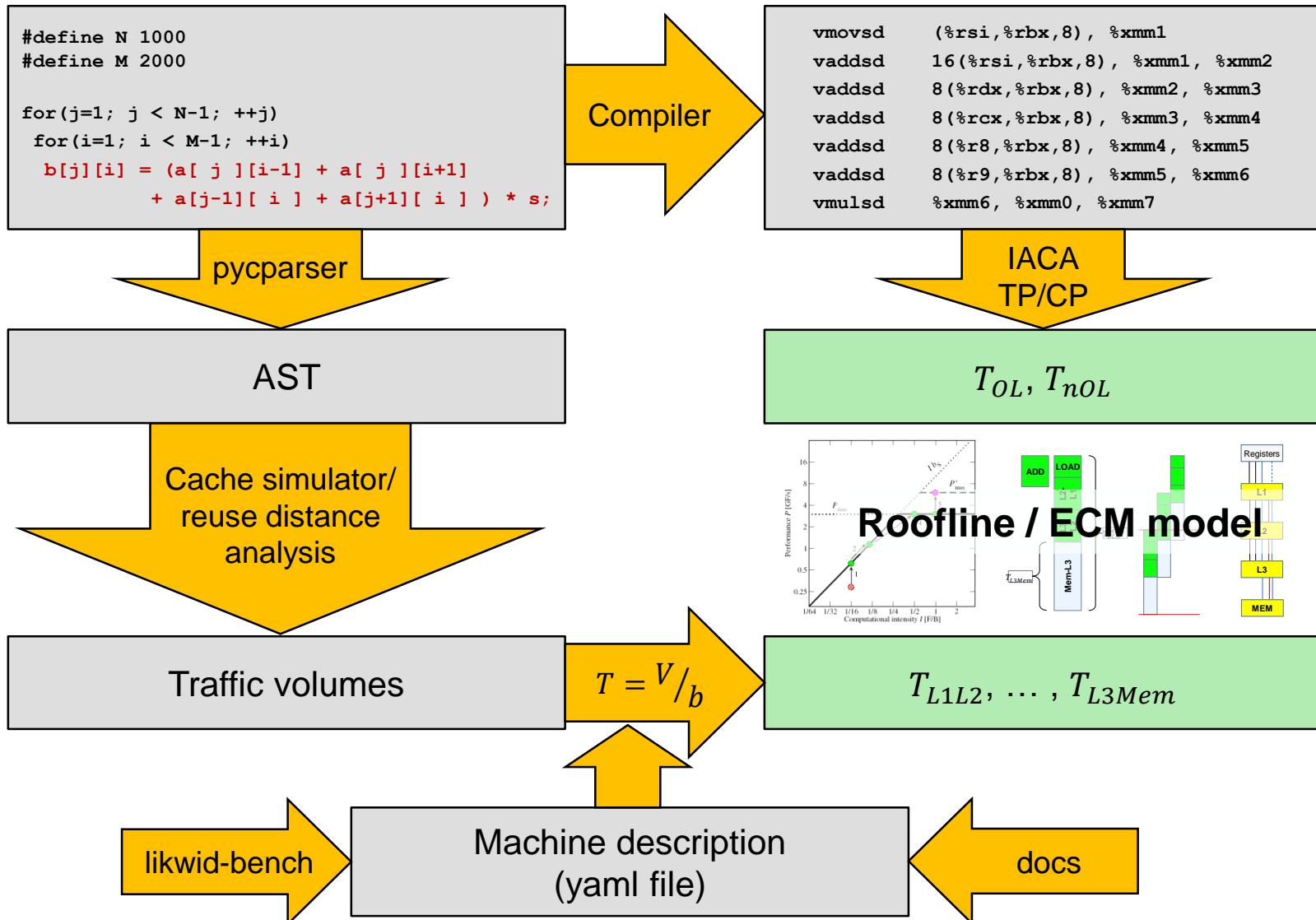
Run: `pip install kerncraft`

Additional requirements are:

- Intel IACA tool, with (working) `iaca.sh` in PATH environment variable (used by ECM, ECMCPU and Roofline models)
- likwid (used in Benchmark model and by `likwid_bench_auto.py`)

Towards automated model generation





Restrictions on code input (selection)

- Only doubles and ints supported
- Array declarations may use fixed sizes or constants, with an optional offset (e.g., double u1[M+3][N-2][23], but not double u[M*N])
- Only the innermost loop may contain assignment statements
- Array references must either use index variables from for-loops, with optional addition or subtraction, constant or fixed values
- All for-loops must use a declaration as initial statement and an increment or a decrement assignment operation as the next statement (e.g., i++, i -= 2)
- Function calls and the use of pointers is not allowed anywhere in the kernel code
- Write access to any data is assumed to use “normal” STORE instructions (e.g., no non-temporal stores)

Operating modes

- **ECM**
 - Full ECM model including in-core analysis
- **ECMDATA**
 - Data traffic analysis only (works on any system)
- **ECMCPU**
 - In-core part of ECM model (IACA)
- **Roofline**
 - Full Roofline model using CPU peak performance as in-core limit
- **RooflineIACA**
 - Full Roofline model using IACA analysis for in-core
- **Benchmark**
 - Run the actual benchmark for model validation

Machine file example: 8-core SNB EP node

```
clock: 2.7 GHz
cores per socket: 8
model type: Intel Core SandyBridge EP processor
model name: Intel(R) Xeon(R) CPU E5-2680 0 @ 2.70GHz
sockets: 2
threads per core: 2
cacheline size: 64 B
icc architecture flags: [-xAVX]
micro-architecture: SNB
FLOPs per cycle:
    SP: {total: 8, ADD: 4, MUL: 4}
    DP: {total: 4, ADD: 2, MUL: 2}
overlapping ports: ["0", "0DV", "1", "2", "3", "4", "5"]
non-overlapping ports: ["2D", "3D"]
memory hierarchy:
- {cores per group: 1, cycles per cacheline transfer: 2,
  groups: 16, level: L1, bandwidth: null, size per group: 32.00
   kB, threads per group: 2}
- {cores per group: 1, cycles per cacheline transfer: 2,
  groups: 16, level: L2, bandwidth: null, size per group: 256.00
   kB, threads per group: 2}
- {bandwidth per core: 18 GB/s, cores per group: 8, cycles per cacheline transfer: null,
  groups: 2, level: L3, bandwidth: 40 GB/s, size per group: 20.00
   MB, threads per group: 16}
- {cores per group: 8, cycles per cacheline transfer: null,
  level: MEM, bandwidth: null, size per group: null, threads per group: 16}
[...]
```

Machine file example (cont.)

```
benchmarks:  
kernels:  
copy:  
    FLOPs per iteration: 0  
    read streams: {bytes: 8.00 B, streams: 1}  
    read+write streams: {bytes: 0.00 B, streams: 0}  
    write streams: {bytes: 8.00 B, streams: 1}  
daxpy:  
    FLOPs per iteration: 2  
    read streams: {bytes: 16.00 B, streams: 2}  
    read+write streams: {bytes: 8.00 B, streams: 1}  
    write streams: {bytes: 8.00 B, streams: 1}  
load:  
    FLOPs per iteration: 0  
    read streams: {bytes: 8.00 B, streams: 1}  
    read+write streams: {bytes: 0.00 B, streams: 0}  
    write streams: {bytes: 0.00 B, streams: 0}  
triad:  
    FLOPs per iteration: 2  
    read streams: {bytes: 24.00 B, streams: 3}  
    read+write streams: {bytes: 0.00 B, streams: 0}  
    write streams: {bytes: 8.00 B, streams: 1}  
update:  
    FLOPs per iteration: 0
```

[...]

Machine file example (cont.)

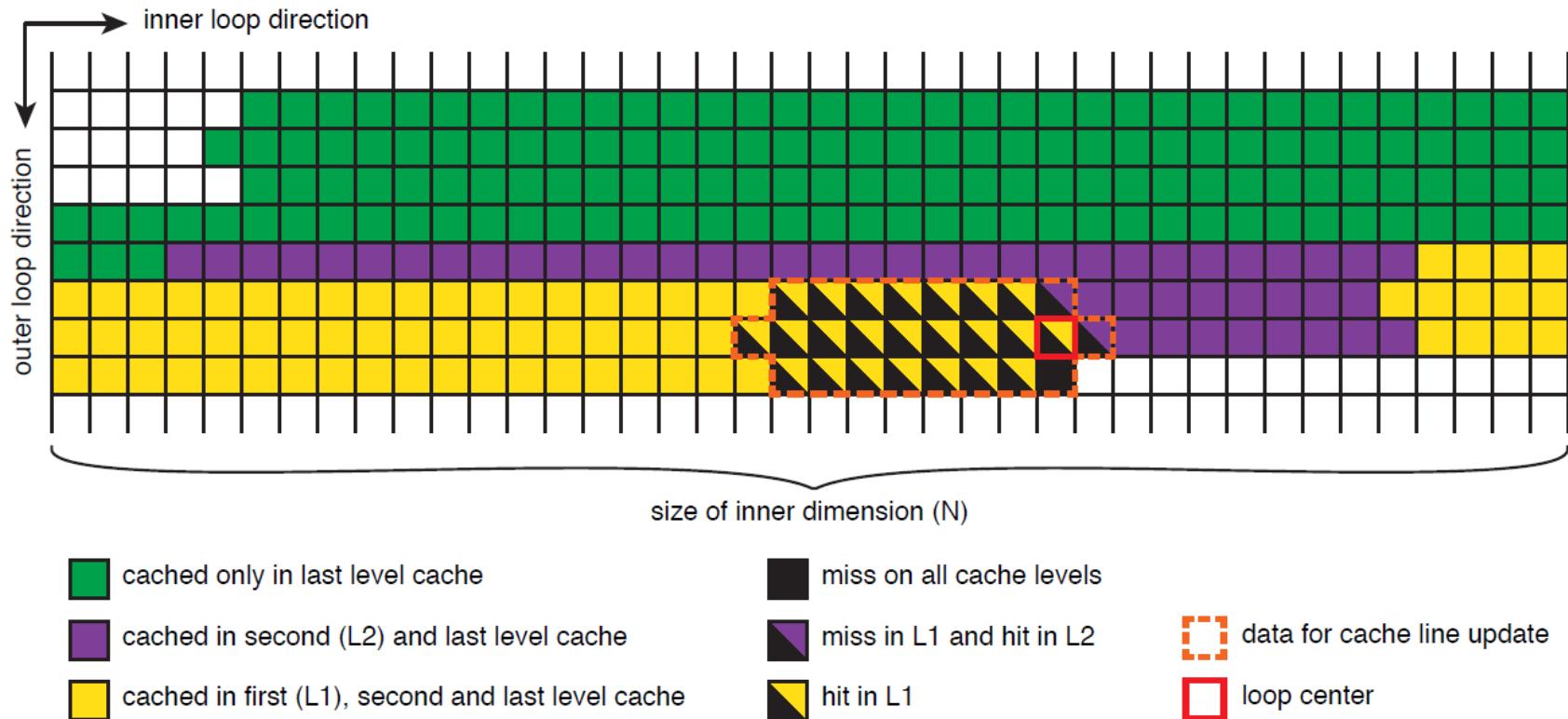
measurements:

[...]

MEM:

```
1:  
cores: [1, 2, 3, 4, 5, 6, 7, 8]  
results:  
    copy: [11.60 GB/s, 21.29 GB/s, 25.94 GB/s, 27.28 GB/s, 27.47 GB/s, 27.36  
           GB/s, 27.21 GB/s, 27.12 GB/s]  
    daxpy: [17.33 GB/s, 31.89 GB/s, 38.65 GB/s, 40.50 GB/s, 40.81 GB/s, 40.62  
            GB/s, 40.59 GB/s, 40.26 GB/s]  
    load: [12.01 GB/s, 23.04 GB/s, 32.79 GB/s, 40.21 GB/s, 43.39 GB/s, 44.14  
           GB/s, 44.42 GB/s, 44.40 GB/s]  
    triad: [12.73 GB/s, 24.27 GB/s, 30.43 GB/s, 31.46 GB/s, 31.77 GB/s, 31.74  
            GB/s, 31.65 GB/s, 31.52 GB/s]  
    update: [18.91 GB/s, 32.43 GB/s, 37.28 GB/s, 39.98 GB/s, 40.99 GB/s, 40.92  
              GB/s, 40.61 GB/s, 40.34 GB/s]  
size per core: [40.00 MB, 20.00 MB, 13.33 MB, 10.00 MB, 8.00 MB, 6.67 MB,  
               5.71 MB, 5.00 MB]  
size per thread: [40.00 MB, 20.00 MB, 13.33 MB, 10.00 MB, 8.00 MB, 6.67 MB,  
                  5.71 MB, 5.00 MB]  
threads: [1, 2, 3, 4, 5, 6, 7, 8]  
threads per core: 1  
total size: [40.00 MB, 40.00 MB, 40.00 MB, 40.00 MB, 40.00 MB, 40.00 MB,  
             40.00 MB, 40.00 MB]
```

Cache reuse analysis



kerncraft usage

```
$ kerncraft -h
usage: kerncraft [-h] [-v[v]] --machine MACHINE
                  --pmodel{ECM,ECMDATA,ECMCPU,Roofline,RooflineIACA,Benchmark}
                  [-D KEY VALUE] [--testcases] [-- testcase-index INDEX]
                  [--verbose] [--asm-block BLOCK] [--store PICKLE]
                  [--ecm-plot ECM_PLOT]
FILE [FILE ...]
```

Examples:

```
$ kerncraft -vv -p ECM -m phinally.yaml 2d-5pt.c -D N 10000 -D M 10000
```

```
$ kerncraft -v -p Roofline -m phinally.yaml 2d-5pt.c -D N 10000 -D M 10000
```

kerncraft example (ECM)

```
$ kerncraft -vv -p ECM -m phinally.yaml 2d-5pt.c -D N 10000 -D M 10000
```

```
=====  
===== 2d-5pt.c  
=====
```

```
double a[M][N];  
double b[M][N];  
double s;  
  
for(int j=1; j<M-1; ++j)  
    for(int i=1; i<N-1; ++i)  
        b[j][i] = ( a[j][i-1] + a[j][i+1]  
                    + a[j-1][i] + a[j+1][i] ) * s;
```

```
variables:      name |      type size
```

a	double	(10000, 10000)
s	double	None
b	double	(10000, 10000)

kerncraft example (ECM) continued

loop stack:

	idx	min	max	step
	j	1	9999	+1
	i	1	9999	+1

data sources:

	name	offsets	...
	a	('rel', 'j', 0), ('rel', 'i', -1)	
		('rel', 'j', 0), ('rel', 'i', 1)	
		('rel', 'j', -1), ('rel', 'i', 0)	
		('rel', 'j', 1), ('rel', 'i', 0)	
	s	('dir',)	

data destinations:

	name	offsets	...
	b	('rel', 'j', 0), ('rel', 'i', 0)	

kerncraft example (ECM) continued

FLOPs:

op	count
<hr/>	
+	3
*	1
<hr/>	
	4

constants:

name	value
<hr/>	
M	10000
N	10000

Ports and cycles: {'1': 6.0, '0DV': 0.0, '2D': 8.0, '0': 5.05, '3': 9.0, '2': 9.0, '5': 5.95, '4': 4.0, '3D': 8.0}

Uops: 37.0

Throughput: 9.45cy per CL

T_nOL = 8.0cy

T_OL = 9.0cy

kerncraft example (ECM) continued

```
Trace length per access in L1: 982
Hits in L1: 30 {'a': {'ji': [10006, 10005, 10004, 10003, 10002, 10001, 10000,
7, 6, 5, 4, 3, 2, 1, 0, -1, -9994, -9995, -9996, -9997, -9998, -9999, -10000]}, 
's': {}, 'b': {'ji': [6, 5, 4, 3, 2, 1, 0]}}
Misses in L1: 4 (4CL): {'a': {'ji': [10007, 8, -9993]}, 's': {}, 'b': {'ji':
[7]}}
Evicts from L1 8 (1CL): {'a': {}, 's': {}, 'b': {'ji': [7, 6, 5, 4, 3, 2, 1,
0]}}}
```

...

L1-L2 = 10cy
L2-L3 = 10cy
L3-MEM = 12.96cy
{ 9.0 || 8.0 | 10 | 10 | 12.96 } cy
{ 9.0 \ 18 \ 28 \ 41 } cy

kerncraft example (Roofline)

```
$ kerncraft -v -p Roofline -m phinally.yaml 2d-5pt.c -D N 10000 -D M 10000
```

...

Bottlenecks:

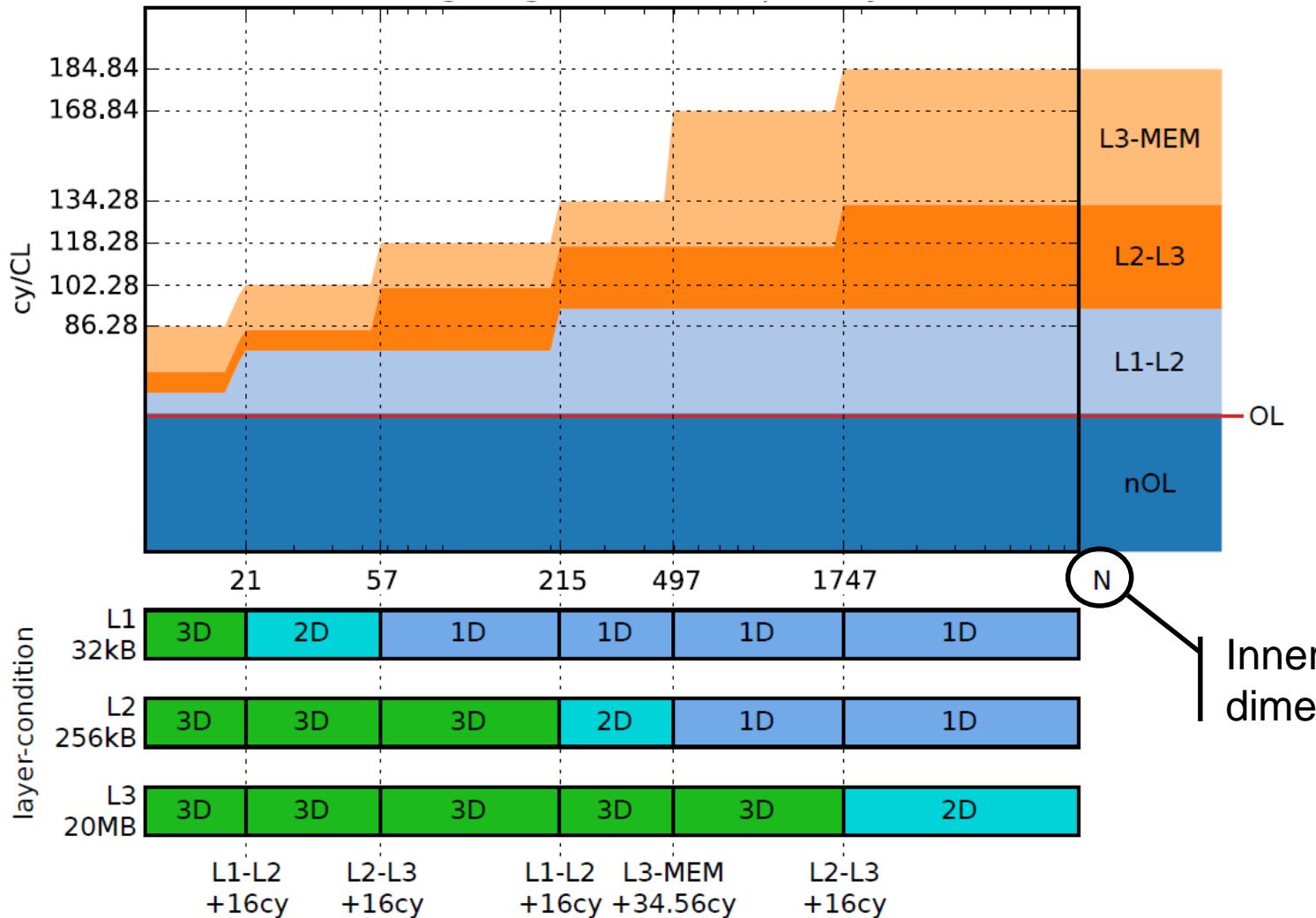
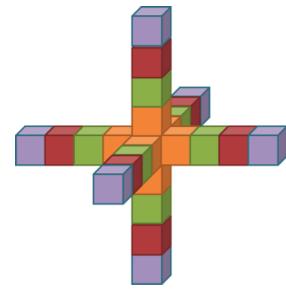
level	a. intensity	performance	bandwidth	bandwidth kernel
CPU		21.60 GFLOP/s		
CPU-L1	0.083 FLOP/b	8.50 GFLOP/s	102.01 GB/s	triad
L1-L2	0.1 FLOP/b	5.12 GFLOP/s	51.15 GB/s	triad
L2-L3	0.1 FLOP/b	3.15 GFLOP/s	31.48 GB/s	triad
L3-MEM	0.17 FLOP/b	2.90 GFLOP/s	17.40 GB/s	copy

Cache or mem bound

2.90 GFLOP/s due to L3-MEM transfer bottleneck (bw with from copy benchmark)

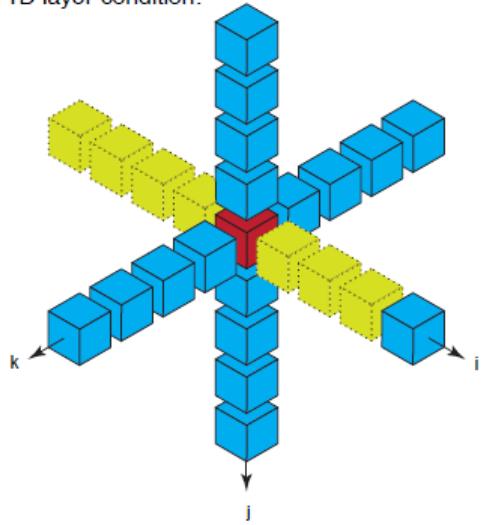
Arithmetic Intensity: 0.17 FLOP/b

Interpretation of predictions: 3D long-range stencil

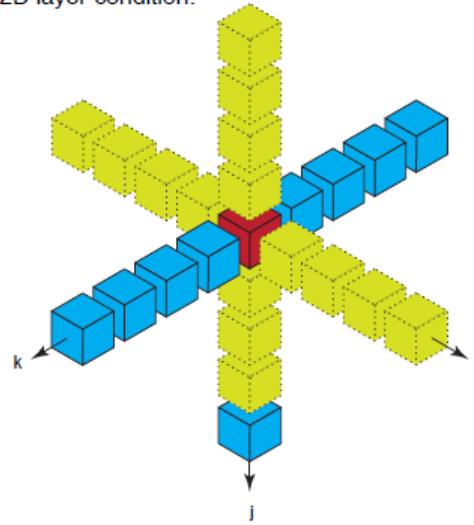


Layer conditions in the 3D long-range stencil

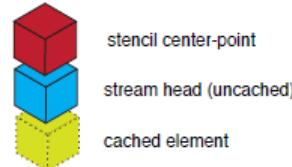
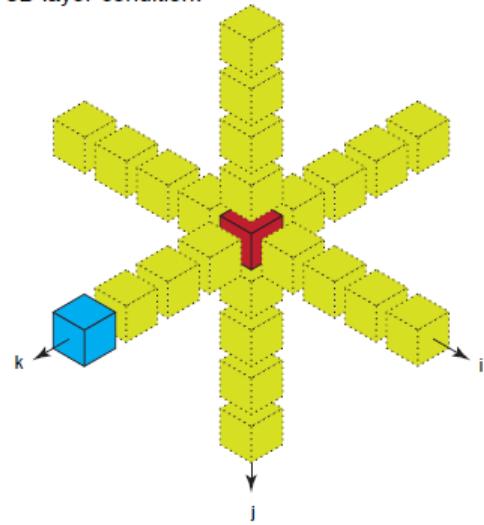
1D layer-condition:



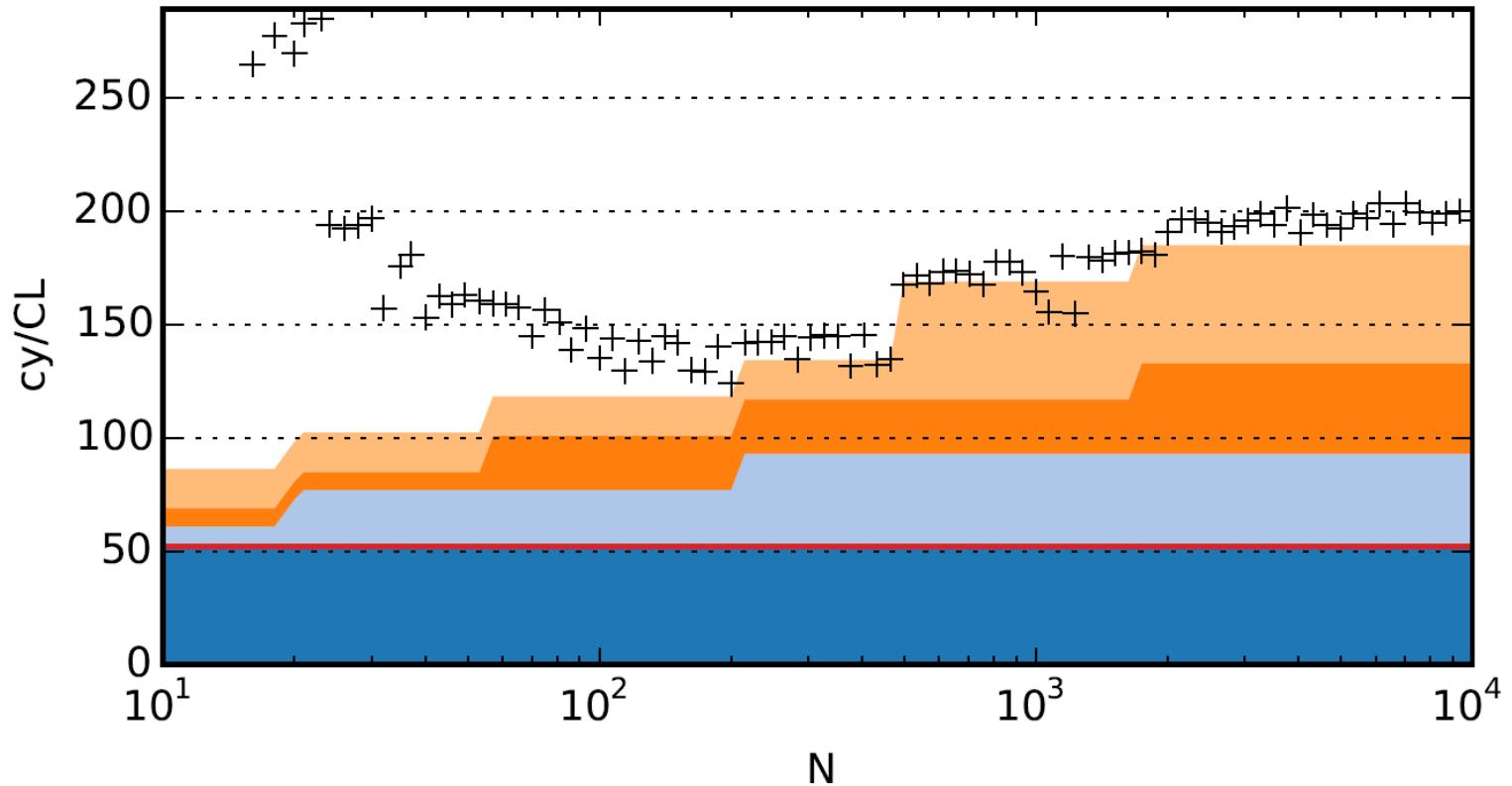
2D layer-condition:



3D layer-condition:



Comparison of measurements with predictions: 3D long-range stencil



Summary & remarks

- No silver bullet
 - Tool output must be checked
 - Validation is absolutely mandatory
 - If the model does not work, we learn something
- Future work
 - Lift some of the restrictions on the C formulation of the loop code
 - Include saturation analysis
 - Become more independent of external tools
 - › IACA,icc
 - Improve simplistic reuse analysis

References

- J. Treibig and G. Hager: *Introducing a Performance Model for Bandwidth-Limited Loop Kernels*. Proceedings of the Workshop “Memory issues on Multi- and Manycore Platforms” at PPAM 2009, the 8th International Conference on Parallel Processing and Applied Mathematics, Wroclaw, Poland, September 13-16, 2009. Lecture Notes in Computer Science Volume 6067, 2010, pp 615-624.
[DOI: 10.1007/978-3-642-14390-8_64](https://doi.org/10.1007/978-3-642-14390-8_64) (2010).
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Thank You.

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