Putting a Dent into the Memory Wall: Combined Power-Performance Modeling for Memory Systems

Laura Carrington, Martin Schulz, & Ananta Tiwari

University of California, San Diego
San Diego Supercomputer Center
Performance Modeling and Characterization Lab (PMaC)

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Research the complex interactions between HPC systems and applications and use that to understand the factors that affect performance and power on current and projected HPC platforms.
Motivation: Entering the era of Exascale – many core systems with strict power budgeting

- Trend towards multi- and many-core systems has accelerated over the last decade –
  - Multi-core designs allow for greater energy efficiency
    - Increase the compute performance through many simple and more energy savings cores
  - More cores/processor → less memory BW per core
    - In particular the off-chip bandwidth which is limited by pin constraints and slowly rising memory speeds
- Exascale comes with strict power budgeting
  - Power capping on the memory sub-system
  - Reduced power → reduced performance

Understand HPC applications sensitivities to these performance/power changes to the memory sub-system

Performance & Power Models provide this understanding
Memory sensitivity models - Modeling an HPC application’s sensitivity to power/performance changes in memory sub-system

Models that capture:

- Application’s sensitivity to reduced per core memory BW (e.g. many core)
- Application’s sensitivity to power capped memory sub-system

Model development:

- Identify software parameters that determine application’s sensitivity to changes
  - How sensitive are different types of computations?
  - Are certain algorithms less sensitive and would result in improved energy efficiency/performance?
Overview

• Brief description of modeling technique:
  – Application characterization
  – Training the model
  – Validation of model
  – Results
  – Use cases
Main goal:

- Develop model that predicts power and performance of application given a change in memory sub-system:
  - Reduced per core memory bandwidth
  - Power capped memory sub-system
HPC Application Model Development – characterizing the application

- Break large scale application into computational phases
HPC Application Model Development – characterizing the application

- Break large scale application into computational phases
- Identify software parameters that determine computational phase’s sensitivity to change (e.g. characterization vector):
  - Data movement of computation (location, stride, type), computation metrics, etc.

Characterization vector = <data movement location, data movement stride, data movement type, computation metrics>
HPC Application Model Development – characterizing the application

- Break large scale application into computational phases
- Identify software parameters that determine computational phase’s sensitivity to change (e.g. characterization vector):
  - Data movement of computation (location, stride, type), computation metrics, etc.

Characterization vector =
<cache hit rates, stride, load/store, FP/mem, # inst., etc. >
HPC Application Model Development – characterizing the application

- Break large scale application into computational phases
- Identify software parameters that determine computational phase’s sensitivity to change (e.g. characterization vector):
  - Data movement of computation (location, stride, type), computation metrics, etc.

Automated full-scale production application collection via

**PEBIL** (PMaC’s Efficient Binary Instrumentor for Linux)
static & dynamic analysis
Modeling Methodology

- **Training set**: use HPC computational kernels & benchmarks (applications are not part of training set)
  - Capture computation vector per kernel
    - Kernel 1: \(<k_1v_1, k_1v_2, \ldots, k_1v_n>\)
    - Kernel 2: \(<k_2v_1, k_2v_2, \ldots, k_2v_n>\)
    - Kernel 3: \(<k_3v_1, k_3v_2, \ldots, k_3v_n>\)
    ...
  - Measure performance of each kernel for target system under change (e.g. reduced per core BW, power cap)
    - Kernel 1: \(<\text{Perf}_{1,90}, \text{Cap90\%}, k_1v_1, k_1v_2, \ldots, k_1v_n>\>
      \(<\text{Perf}_{1,80}, \text{Cap80\%}, k_1v_1, k_1v_2, \ldots, k_1v_n>\>
      \(<\text{Perf}_{1,70}, \text{Cap70\%}, k_1v_1, k_1v_2, \ldots, k_1v_n>\>
      ...
    - Kernel 2: \(<\text{Perf}_{2,90}, \text{Cap90\%}, k_2v_1, k_2v_2, \ldots, k_2v_n>\>
      \(<\text{Perf}_{2,80}, \text{Cap80\%}, k_2v_1, k_2v_2, \ldots, k_2v_n>\>
      \(<\text{Perf}_{2,70}, \text{Cap70\%}, k_2v_1, k_2v_2, \ldots, k_2v_n>\>
      ...

Modeling Methodology

Training set:
\(<Perf_{1,90}, Cap_{90}\%, k_1 v_1, k_1 v_2, \ldots k_1 v_n>\>
\(<Perf_{1,80}, Cap_{80}\%, k_1 v_1, k_1 v_2, \ldots k_1 v_n>\>
\(<Perf_{1,70}, Cap_{70}\%, k_1 v_1, k_1 v_2, \ldots k_1 v_n>\>
\ldots
\(<Perf_{2,90}, Cap_{90}\%, k_2 v_1, k_2 v_2, \ldots k_2 v_n>\>
\(<Perf_{2,80}, Cap_{80}\%, k_2 v_1, k_2 v_2, \ldots k_2 v_n>\>
\(<Perf_{2,70}, Cap_{70}\%, k_2 v_1, k_2 v_2, \ldots k_2 v_n>\>
\ldots

- Modeling technique Cubist (e.g., tree of linear regression models) & Gradient Boosting

- Prevent over-fitting:
  - Split the empirical dataset into training and validation sets
    - 60%-40% split: 60% used for training the model and 40% for validation
  - 10-fold cross validation to avoid over-fitting during model training

- Variable importance analysis to determine which predictors have the most impact on performance degradation
Modeling reduced per core memory BW

System Configuration for Validation
testing with the Imbench benchmark

- How to approximate reduced per core memory BW?
  - Change the memory bus frequency (set at boot time)

- One node of the SDSC’s Gordon Supercomputer
  - Sandy Bridge – 2 procs, 8 cores/proc, 64GB DDR3-1333MHz memory
  - Available bus freq. – 1333 MHz (max & default), 1067 MHz, 800 MHz

\[ \text{MEM BW (theoretical)} = F \times L \times W \times I \]

where,
- \( F \): DRAM clock frequency
- \( L \): Number of lines per clock (2 for DDRN)
- \( W \): Bus Width (64 bits)
- \( I \): Number of Interfaces (2: dual channel)

800MHz: 37.7% reduction in BW when frequency is reduced by 40%

1067MHz: 17.5% reduction in BW when freq is reduced by 20%.
Are all computations sensitive to per core bandwidth?

Ratio of training set kernels and benchmark’s performance at max relative to reduced BW

Effect of Memory Bus Frequency on Execution Time

1333 MHz -> 1067 MHz

1333 MHz -> 800 MHz

Ratio of 1 means performance not affected

Unaffected: 43%

Unaffected: 35%
Model accuracy on training Set for reduced per core memory BW model prediction of ratio of degradation

Abs. Mean Error: 0.8%
Max Error: 17.6%
Evaluation of modeling methodology

- Evaluation uses several applications –
  - NPBs (CG, LU, FT and MG)
  - SMG2000 (Semi-coarsening multigrid)
  - AMG (Algebraic multigrid)
  - Mantevo Miniapps
    - MiniFE
    - MiniGhost
  - CoMD

- Hotspot selection based on dynamic instruction count attributed to loops

- Verify model on dominant loop(s)/phase(s) of application \(\rightarrow\) collect characterization vector
Model validation – Mantevo & CoMD

Mantevo Miniapps (MiniGhost and MiniFE) and CoMD, 16 Cores
Performance Sensitivity of dominant phases (256 x 256 x 256)

- Measured MiniGhost (P1)
- Modeled MiniGhost (P1)
- Measured MiniFE (P1)
- Modeled MiniFE (P1)
- Measured CoMD (P1)
- Modeled CoMD (P1)

Memory Bus Frequency (MHz)

Time wrt to the highest (1333 MHz) Frequency

- MiniFE (Sparse MVec)
- MiniGhost (Stencil)
- CoMD (ljForce)
Model validation: AMG

AMG, 16 Cores
Performance Sensitivity of 4 dominant phases (256 x 256 x 256)

Time wrt to the highest (1333 MHz) Frequency

Memory Bus Frequency (MHz)
Model validation: Mean Error of all phases

Histogram of Prediction Accuracy for Test Application’s Phases

Mean Error: 3.8%
Max Error: 18%

91% of the evaluated phases (Error < 10%)

Outliers (total 8 phase-freq pairs):
Small grid size runs for miniGhost and SMG2000
One phase from NPB FT.
Use-Case: Algorithm selection

- Exascale systems will most likely have reduced per core memory bandwidth. Models help identify optimal algorithms for these systems.

Determining the correct algorithm for future Exascale systems using performance models:

Parasails has the fastest performance.

Parasails is most sensitive to reductions in BW.

Performance models can identify algorithmic choices that are less optimal as hardware changes in future systems.
Test bed for power capping

- Dual Intel SandyBridge processor, 8 cores per processor, 64 GB RAM, Turbo-Boost off, SMT off

- Power capping using Running Average Power Limit (RAPL) interface
  - Enables the collection of (modeled) power measurements for CPU and DRAM subsystems
  - Allows users to set power limits on these domains and the underlying hardware infrastructure enforces these power limits
Results: Model Accuracy for power capping

60%-40% split of the empirical data.

60% used for training the model

40% makes up the test/validation set.
Results: Evaluation on Mini-apps

- Evaluation done using two mini-apps –
  - MiniGhost (Finite Difference)
  - CoMD (Molecular Dynamics)

- Multiple input sizes

- Loop selection based on dynamic instruction count attributed to loops
  - Compare actual performance loss due to different power caps to modeled performance loss
Results: Evaluation on Mini-apps

Average absolute error: 6%
Use-case: Auto-tuning in power-capped environment

- Search-based auto-tuning framework
  - Generate a set of alternative implementations of a given piece of code and select the one that performs the best
  - The code variant that performs the best in base-case (i.e., with no power capping) might not be the best in power-capped environment
  - Model can be used to inform such explorations

- Demonstration using one computation kernel
  - Select 100 random variants, evaluate the performance of those variants in multiple power capping levels

Models identify optimal variant for given power cap
Use-case: Auto-tuning

- Models identify code optimal code variant for a given power budget.
- X-axis shows small subset of 100 code variants, Y-axis different DRAM power reductions relative to base.
- Green dot shows fastest code variant for each power bounds.
- Red dot only case where models didn’t identify fastest code variant.

Fastest code variant for 14% power cap
Row is performance for each variant under that % capping.
Summary

- Exascale will have multi-core designs and power capped environment that will expose new performance challenges to HPC application developers.
- Models help developers and centers enhance their readiness for Exascale systems and beyond;
  - For their key workloads, models can identify code-sections that need to be re-examined to exploit drastic changes in Exascale hardware design.
- Presented models that are highly accurate in predicting the performance sensitivity of various HPC computations for power caps DRAM domains as well as reduce per core memory BW.
- Presented use cases for both types of models.

Thank you for your attention!
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For further details:
Questions